

FIXED POINT THEOREMS FOR WEAK C-CONTRACTIONS  
AND WEAKLY COMPATIBLE MAPPINGS IN 2-METRIC SPACE

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ABSTRACT

The purpose of this paper is to study a common fixed point theorem on 2-metric space using weak C-contraction and weakly compatibility. We mainly generalize the result of Dung and Hang [6], which unifies and generalizes many results in the literature.

*Mathematics Subject Classification:* 47H10, 54H25.

*Key Words:* 2-metric space, weak C contraction, weak compatible maps, Fixed point.

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INTRODUCTION

The concept of 2-metric space is a natural generalization of a metric space. It has been investigated initially by Gahler [7]. Then many researchers like Iseki [8], Rhoades [13], Simoniya [14] etc. prove many fixed points in this space. Gahler [7] introduce 2-metric space as

Let  $X$  be a non-empty set and let  $d: X \times X \times X \rightarrow [0, \infty)$  be such that

- (i) For every pair of distinct point  $x, y$  in  $X$  with  $x \neq y$  there exists a point  $z$  in  $X$  such that  $d(x, y, z) \neq 0$ .
- (ii)  $d(x, y, z) = 0$  when at least two of the three points are equal.
- (iii) For any  $x, y, z$  in  $X$ ,  $d(x, y, z) = d(x, z, y) = d(y, z, x)$ .
- (iv) For any  $x, y, z, w$  in  $X$ ,  $d(x, y, z) \leq d(x, y, w) + d(x, w, z) + d(w, y, z)$ .

Then  $d$  is called a 2-metric [4] and  $(X, d)$  is called a 2-metric space [4].

A sequence  $\{x_n\}$  in  $X$  is called a Cauchy sequence [7] when  $d(x_n, x_m, a) \rightarrow 0$  as  $n, m \rightarrow \infty$

A sequence  $\{x_n\}$  in  $X$  is said to be converge [7] to an element  $x$  in  $X$  when  $d(x_n, x, a) \rightarrow 0$  as  $n \rightarrow \infty$

A 2-metric space  $(X, d)$  is said to be complete if every Cauchy sequence in  $X$  converges to a point of  $X$ .

Naidu and Prasad [12] proved that every convergent sequence need not be a Cauchy sequence in 2-metric space. Chatterjea [2] introduced the notion of a C-contraction.

**Definition: [2]** Let  $(X, d)$  be a metric space and  $T: X \rightarrow X$  be a map. Then  $T$  is called a C-contraction if there exists  $\alpha \in (0, 1/2)$  such that for all  $x, y \in X$ ,

$$d(Tx, Ty) \leq \alpha[d(x, Ty) + d(y, Tx)].$$

C-contraction was generalized to weak C-contraction by Choudhury [4] as

**Definition: [4]** Let  $(X, d)$  be a metric space and  $T: X \rightarrow X$  be a map. Then  $T$  is called a weak C-contraction if there exists  $\psi: [0, \infty)^2 \rightarrow [0, \infty)$  which is continuous and  $\psi(s, t) = 0$  if and only if  $s = t = 0$  such that

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(y, Tx)] - \psi(d(x, Ty), d(y, Tx)) \text{ for all } x, y \in X.$$

Choudhury [4] proved that if  $X$  is a complete metric space, then every weak C-contraction has a fixed point. Dung and Hang [6] proved a fixed point theorem for weak C-contraction in partially ordered 2-metric space for one mapping.

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In this paper, we will prove common fixed point theorem for four mappings in 2-metric space with the help of weak C-contraction and weakly compatible mappings by using  $\psi(a, b) = \frac{1}{2} \min\{a, b\}$ .

**MAIN RESULTS**

**Theorem:** Let,  $(X, d)$  be a complete 2-metric space, and  $F, G, S,$  and  $T$  be self maps of  $X$  satisfying  $S(X) \subseteq F(X), T(X) \subseteq G(X)$  and weak C contraction such that

$$d(Sx, Ty, u) \leq \frac{1}{2} [d(Gx, Ty, u) + d(Fy, Sx, u)] - \psi(d(Gx, Ty, u), d(Fy, Sx, u)) \tag{1}$$

for all  $x, y$  in  $X$  and  $\psi: [0, \infty)^2 \rightarrow [0, \infty)$  which is continuous and  $\psi(s, t) = 0$  if and only if  $s = t = 0$  and  $F(X)$  and  $G(X)$  are closed subsets of  $X$ .  $(T, F)$  and  $(S, G)$  are weakly compatible. Then,  $F, G, S$  and  $T$  have a unique common fixed point in  $X$ .

**Proof:** Let  $x_0$  be any point in  $X$  and as  $S(X) \subseteq F(X), T(X) \subseteq G(X)$  then there exists  $x_1, x_2$  in  $X$  such that  $Sx_0 = Fx_1, Tx_1 = Gx_2$

Inductively, we can construct sequences  $\{x_n\}$  and  $\{y_n\}$  in  $X$  such that  $y_n = Sx_n = Fx_{n+1}$  and  $y_{n+1} = Tx_{n+1} = Gx_{n+2}, n=0, 1, 2, \dots$

Now,

$$\begin{aligned} d(y_n, y_{n+1}, u) &= d(Sx_n, Tx_{n+1}, u) \leq \frac{1}{2} [d(Gx_n, Tx_{n+1}, u) + d(Fx_{n+1}, Sx_n, u)] - \psi(d(Gx_n, Tx_{n+1}, u), d(Fx_{n+1}, Sx_n, u)) \\ &= \frac{1}{2} [d(y_{n-1}, y_{n+1}, u) + d(y_n, y_n, u)] - \psi(d(y_{n-1}, y_{n+1}, u), d(y_n, y_n, u)) \\ &= \frac{1}{2} d(y_{n-1}, y_{n+1}, u) - \psi(d(y_{n-1}, y_{n+1}, u), 0) \\ &\leq \frac{1}{2} d(y_{n-1}, y_{n+1}, u) \end{aligned} \tag{2}$$

$$\text{Now, if we put } u = y_{n-1} \text{ in (3) then we get, } d(y_n, y_{n+1}, y_{n-1}) \leq 0. \tag{4}$$

Now, from (3) and (4) we get,

$$\begin{aligned} d(y_n, y_{n+1}, u) &\leq \frac{1}{2} d(y_{n-1}, y_{n+1}, u) \leq \frac{1}{2} [d(y_{n-1}, y_{n+1}, y_n) + d(y_{n-1}, y_n, u) + d(y_n, y_{n+1}, u)] \\ &= \frac{1}{2} [d(y_{n-1}, y_n, u) + d(y_n, y_{n+1}, u)]. \end{aligned} \tag{5}$$

$$\text{Which gives that, } d(y_n, y_{n+1}, u) \leq d(y_{n-1}, y_n, u) \tag{6}$$

So,  $\{d(y_n, y_{n+1}, u)\}$  is a non-negative decreasing sequence and hence it is convergent.

$$\text{Let, } d(y_n, y_{n+1}, u) = r \tag{7}$$

$$\begin{aligned} \text{Taking } \lim_{n \rightarrow \infty} \text{ in (4) and using (6) we get, } r &\leq \frac{1}{2} d(y_{n-1}, y_{n+1}, u) \leq \frac{1}{2}(r+r) = r \\ \text{i.e., } d(y_{n-1}, y_{n+1}, u) &= 2r \end{aligned} \tag{8}$$

$$\begin{aligned} \text{Taking } \lim_{n \rightarrow \infty} \text{ in (2) and using (7) and (8) we get, } r &\leq \frac{1}{2} \cdot 2r - \psi(0, 2r) \\ \text{i.e., } \psi(0, 2r) &\leq 0 \text{ which shows that } r = 0 \end{aligned}$$

$$\text{So, from (7) we get, } \lim_{n \rightarrow \infty} d(y_n, y_{n+1}, u) = 0 \tag{9}$$

Now, we will prove that  $\{y_n\}$  is a Cauchy sequence.

$$\begin{aligned} \text{Now, } d(y_n, y_{n+2}, u) &\leq d(y_n, y_{n+2}, y_{n+1}) + d(y_n, y_{n+1}, u) + d(y_{n+1}, y_{n+2}, u) \\ &= d(y_n, y_{n+2}, y_{n+1}) + \sum_{r=0}^1 d(y_{n+r}, y_{n+r+1}, u). \end{aligned} \tag{10}$$

$$\begin{aligned} \text{Now, } d(y_n, y_{n+2}, y_{n+1}) &= d(y_{n+1}, y_{n+2}, y_n) = d(Sx_{n+1}, Tx_{n+2}, y_n) \\ &\leq \frac{1}{2} [d(Gx_{n+1}, Tx_{n+2}, y_n) + d(Fx_{n+2}, Sx_{n+1}, y_n)] - \psi(d(Gx_{n+1}, Tx_{n+2}, y_n), d(Fx_{n+2}, Sx_{n+1}, y_n)) \\ &= \frac{1}{2} [d(y_n, y_{n+2}, y_n) + d(y_{n+1}, y_{n+1}, y_n)] - \psi(d(y_n, y_{n+2}, y_n), d(y_{n+1}, y_{n+1}, y_n)) \\ &= \frac{1}{2} [0+0] - \psi(0, 0) = 0 \end{aligned} \tag{11}$$

$$\text{Putting the value of (11) in (10) we get, } d(y_n, y_{n+2}, u) \leq \sum_{r=0}^1 d(y_{n+r}, y_{n+r+1}, u)$$

Similarly proceeding as above we will get,

$$d(y_n, y_{n+p}, u) \leq \sum_{r=0}^{p-1} d(y_{n+r}, y_{n+r+1}, u)$$

Taking  $\lim_{n \rightarrow \infty}$  on the above inequality we get,  $\lim_{n \rightarrow \infty} d(y_n, y_{n+p}, u) = 0$  (by (9))

Which shows that  $\{y_n\}$  is a Cauchy sequence in X.

Since, G(X) is complete then  $\{y_n\}$  converges to a point z in G(X). i.e.,  $\lim_{n \rightarrow \infty} y_n = z$ .

Since,  $T(X) \subset G(X)$ , then there exists a point q in X such that  $Gq = z$  (12)

$$\begin{aligned} \text{Now, } d(Sq, y_{n+1}, u) &= d(Sq, Tx_{n+1}, u) \\ &\leq \frac{1}{2} [d(Gq, Tx_{n+1}, u) + d(Fx_{n+1}Sq, u)] - \psi(d(Gq, Tx_{n+1}, u), d(Fx_{n+1}, Sq, u)) \end{aligned}$$

Taking  $\lim_{n \rightarrow \infty}$  on the above inequality and using (12) we get,

$$\begin{aligned} d(Sq, z, u) &= d(Sq, z, u) \leq \frac{1}{2} [d(z, z, u) + d(z, Sq, u)] - \psi(d(z, z, u), d(z, Sq, u)) \\ &= \frac{1}{2} d(z, Sq, u) - \psi(0, d(z, Sq, u)) \leq \frac{1}{2} d(z, Sq, u) \end{aligned}$$

i.e,  $d(z, Sq, u) \leq 0$  i.e.,  $d(z, Sq, u) = 0$

So,  $Sq = z$ . (13)

From (12) & (13) we get,  $Gq = z = Sq$  (14)

Again, (S, G) are weakly compatible so  $SGq = GSq$  i.e.,  $Sz = Gz$  (by (14)) (15)

$$\begin{aligned} \text{Now, } d(Sz, y_{n+1}, u) &= d(Sz, Tx_{n+1}, u) \\ &\leq \frac{1}{2} [d(Gz, Tx_{n+1}, u) + d(Fx_{n+1}Sz, u)] - \psi(d(Gz, Tx_{n+1}, u), d(Fx_{n+1}, Sz, u)) \end{aligned}$$

Taking  $\lim_{n \rightarrow \infty}$  on the above inequality and using (15) we get,

$$\begin{aligned} d(Sz, z, u) &\leq \frac{1}{2} [d(Sz, z, u) + d(z, Sz, u)] - \psi(d(Sz, z, u), d(z, Sz, u)) \text{ (by (15))} \\ &= d(Sz, z, u) - \psi(d(Sz, z, u), d(z, Sz, u)) \end{aligned}$$

i.e,  $\psi(d(Sz, z, u), d(z, Sz, u)) \leq 0$

So,  $Sz = z$

From (15) we get,  $Sz = z = Gz$  (16)

Since,  $S(X) \subset F(X)$ , then there exists a point p in X such that  $Fp = z$ . (17)

$$\begin{aligned} \text{Now, } d(y_n, Tp, u) &= d(Sx_n, Tp, u) \\ &\leq \frac{1}{2} [d(Gx_n, Tp, u) + d(Fp, Sx_n, u)] - \psi(d(Gx_n, Tp, u), d(Fp, Sx_n, u)) \end{aligned}$$

Taking  $\lim_{n \rightarrow \infty}$  on the above inequality and using (12) we get,

$$\begin{aligned} d(z, Tp, u) &\leq \frac{1}{2} [d(z, Tp, u) + d(z, z, u)] - \psi(d(z, Tp, u), d(z, z, u)) \\ &= \frac{1}{2} d(z, Tp, u) - \psi(d(z, Tp, u), 0) \leq \frac{1}{2} d(z, Tp, u) \end{aligned}$$

i.e,  $d(z, Tp, u) \leq 0$  i.e.,  $d(z, Tp, u) = 0$

So,  $Tp = z$  (18)

From (17) and (18) we get,  $Fp = z = Tp$  (19)

As (T, F) are weakly compatible then,  $TFp = FTp$  i.e.,  $Tz = Fz$  (by (19)) (20)

$$\begin{aligned} \text{Now, } d(y_n, Tz, u) &= d(Sx_n, Tz, u) \\ &\leq \frac{1}{2} [d(Gx_n, Tz, u) + d(Fz, Sx_n, u)] - \psi(d(Gx_n, Tz, u), d(Fz, Sx_n, u)) \end{aligned}$$

Taking  $\lim_{n \rightarrow \infty}$  on the above inequality and using (20) we get,

$$\begin{aligned} d(z, Tz, u) &\leq \frac{1}{2} [d(z, Tz, u) + d(Tz, z, u)] - \psi(d(z, Tz, u), d(Tz, z, u)) \text{ (by (20))} \\ &= d(z, Tz, u) - \psi(d(z, Tz, u), d(Tz, z, u)) \end{aligned}$$

i.e.,  $\psi(d(z, Tz, u), d(Tz, z, u)) \leq 0$

By the property of  $\psi$  it is only possible when,  $d(Tz, z, u) = 0$  i.e.,  $Tz = z$

So, from (20) we get,  $Tz = z = Fz$  (21)

From (16) & (20) we get,  $Tz = Fz = z = Sz = Gz$

So,  $z$  is a common fixed point of  $S, F, G$  and  $T$ . (22)

Now, we will prove that  $z$  is a unique fixed point.

If possible late,  $w(\neq z)$  is also a fixed point of  $S, G, F$  and  $T$ .

Now,  $d(z, w, u) = d(Sz, Tw, u)$

$$\leq \frac{1}{2} [d(Gz, Tw, u) + d(Fw, Sz, u)] - \psi(d(Gz, Tw, u), d(Fw, Sz, u))$$

$$= \frac{1}{2} [d(z, w, u) + d(w, z, u)] - \psi(d(z, w, u), d(w, z, u))$$

$$= d(z, w, u) - \psi(d(z, w, u), d(w, z, u))$$

i.e.,  $\psi(d(z, w, u), d(w, z, u)) \leq 0$

By the property of  $\psi$  it is only possible when,  $d(z, w, u) = 0$  i.e.,  $z = w$

So,  $z$  is a unique fixed point of  $S, G, F$  and  $T$ .

## CONCLUSION

In this paper we prove the main theorem for four mappings with the help of weak C-contraction and weakly compatible mappings. Dung and Hang [6] prove their main theorem for only one mapping with the help of weak C-contraction. So, this paper is a generalization of [6]. Changing the condition of  $\psi(a, b)$  we will get many generalization of this result.

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