

COMMON FIXED POINTS
FOR FOUR MAPS USING α – ADMISSIBLE FUNCTIONS IN METRIC SPACES

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ABSTRACT

In this paper, we introduce α – admissible function associated with four maps and obtain a unique common fixed point theorem. We also give an example to illustrate our main theorem.

Keywords: Complete metric spaces, α – admissible functions, Compatible mappings

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1. INTRODUCTION AND PRELIMINARIES

In 1973, Geraghty [3] introduced an interesting class of auxiliary functions to refine the Banach contraction mapping principle. Let \mathcal{F} denote a set of all functions $\beta : [0, \infty) \rightarrow [0, 1)$ satisfying the condition

$$\lim_{n \rightarrow \infty} \beta(t_n) = 1 \quad \text{implies} \quad \lim_{n \rightarrow \infty} t_n = 0.$$

By using the function $\beta \in \mathcal{F}$, Geraghty [3] proved the following remarkable theorem.

Theorem 1.1 [3]: Let (X, d) be a complete metric space and $T : X \rightarrow X$ be an operation. If T satisfies $d(Tx, Ty) \leq \beta(d(x, y))d(x, y)$ for all $x, y \in X$, where $\beta \in \mathcal{F}$, then T has a unique fixed point in X.

Definition 1.2: Let Ψ denote the class of all functions $\psi : [0, \infty) \rightarrow [0, \infty)$ which satisfy the following conditions

- (a) ψ is non-decreasing and continuous,
- (b) $\psi(t) = 0 \Leftrightarrow t = 0$.

Definition 1.3 [4]: Let f and g be self mappings on a metric space (X, d) . The pair (f, g) is said to be compatible if $d(fgx_n, gfx_n) \rightarrow 0$ whenever there exists a sequence $\{x_n\}$ in X such that $fx_n \rightarrow z$ and $gx_n \rightarrow z$ for some $z \in X$.

Samet *et.al* [6] introduced the notion of α – admissible mappings as follows

Definition 1.4 [6]: Let X be a non empty set, $T : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, \infty)$ be mappings. Then T is called α – admissible if for all $x, y \in X$, we have $\alpha(x, y) \geq 1$ implies $\alpha(Tx, Ty) \geq 1$.

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Some interesting examples of such mappings are given in [6]. Actually, they proved the following

Theorem 1.5 [6]: Let (X, d) be a complete metric space. Suppose that $\alpha : X \times X \rightarrow [0, \infty)$ and $\phi : [0, \infty) \rightarrow [0, \infty)$, where ϕ is non-decreasing and $\sum \phi^n(t) < \infty$ for each $t > 0$. Suppose that $T : X \rightarrow X$ satisfies $\alpha(x, y)d(Tx, Ty) \leq \phi(d(x, y))$ for all $x, y \in X$.

Assume the following

- (i) T is α – admissible,
- (ii) there exists $x_0 \in X$ such that $\alpha(x_0, Tx_0) \geq 1$,
- (iii) either T is continuous or if $\{x_n\}$ is a sequence in X with $\alpha(x_n, x_{n+1}) \geq 1$ for all $n \in \mathcal{N}$ (the set of all natural numbers) and $x_n \rightarrow x$ as $n \rightarrow \infty$, then $\alpha(x_n, x) \geq 1$ for all $n \in \mathcal{N}$.

Then T has a fixed point in X .

Further, if for any $x, y \in X$, there exists $z \in X$ such that $\alpha(x, z) \geq 1$ and $\alpha(y, z) \geq 1$ then T has a unique fixed point in X .

Recently, Karapinar *et.al* [5] defined the notion of triangular α – admissible mappings as follows

Definition 1.6 [5]: Let X be a non empty set, $T : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, \infty)$. Then T is called triangular α – admissible if

- (i) $x, y \in X, \alpha(x, y) \geq 1 \Rightarrow \alpha(Tx, Ty) \geq 1$
- (ii) $x, y, z \in X, \alpha(x, z) \geq 1$ and $\alpha(z, y) \geq 1 \Rightarrow \alpha(x, y) \geq 1$.

Later Shahi *et.al* [7] and Abdeljawad [1] defined the following

Definition 1.7 [7]: Let X be a non empty set, $f, g : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, \infty)$. Then f is said to be α – admissible with respect to g if $\alpha(gx, gy) \geq 1$ implies $\alpha(fx, fy) \geq 1$ for all $x, y \in X$.

Definition 1.8 [1]: Let X be a non empty set, $f, g : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, \infty)$. Then the pair (f, g) is said to be α – admissible if $\alpha(x, y) \geq 1$ implies $\alpha(fx, gy) \geq 1$ and $\alpha(gx, fy) \geq 1$ for all $x, y \in X$.

Using these definitions, we introduce the following

Definition 1.9: Let X be a non empty set and $f, g, S, T : X \rightarrow X$ and $\alpha : X \times X \rightarrow [0, \infty)$. The pair (f, g) is said to be α – admissible w.r.to the pair (S, T)

if $\alpha(Sx, Ty) \geq 1$ implies $\alpha(fx, gy) \geq 1$ and $\alpha(Tx, Sy) \geq 1$ implies $\alpha(gx, fy) \geq 1$.

Definition 1.10: (f, g) is called triangular α – admissible w.r.to (S, T) if

- (i) (f, g) is α – admissible w.r.to (S, T) and
- (ii) $\alpha(x, y) \geq 1$ and $\alpha(y, z) \geq 1 \Rightarrow \alpha(x, z) \geq 1$ for all $x, y, z \in X$.

Recently Shahi *et.al* [7] and Cho *et.al* [2] proved the following

Theorem 1.11 (Theorem 3.1, [7]): Let (X, d) be a complete metric space and $f, g : X \rightarrow X$ be such that $f(X) \subseteq g(X)$. Assume the following

- (1.12.1) f is α – admissible with respect to g ,
- (1.12.2) $\alpha(gx, gy)d(fx, fy) \leq \psi(M(gx, gy))$, where

$$M(gx, gy) = \max \left\{ d(gx, gy), \frac{d(gx, fx) + d(gy, fy)}{2}, \frac{d(gx, fy) + d(gy, fx)}{2} \right\} \text{ and}$$

$\psi : [0, \infty) \rightarrow [0, \infty)$ is continuous, nondecreasing and $\sum_{n=1}^{\infty} \psi^n(t) < \infty$ for all $t > 0$,

(1.12.3) there exists $x_0 \in X$ such that $\alpha(gx_0, fx_0) \geq 1$,

(1.12.4) if $\{gx_n\}$ is a sequence in X such that $\alpha(gx_n, gx_{n+1}) \geq 1$, for all n and

$gx_n \rightarrow gz \in g(X)$, then there exists a subsequence $\{gx_{n_k}\}$ of $\{gx_n\}$ such that $\alpha(gx_{n_k}, gz) \geq 1$, for all k .

Also suppose that $g(X)$ is closed.

Then f and g have a coincidence point.

Theorem 1.12 (Theorem 2.1, [2]): Let (X, d) be a complete metric space $\alpha : X \times X \rightarrow [0, \infty)$ be a function and $T : X \rightarrow X$. suppose that the following conditions are satisfied

(1.13.1) $\alpha(x, y)d(Tx, Ty) \leq \beta(M(x, y))M(x, y)$ for all $x, y \in X$, where $\beta \in \mathcal{F}$ and

$$M(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty)\},$$

(1.13.2) T is triangular α – admissible,

(1.13.3) there exists $x_1 \in X$ such that $\alpha(x_1, Tx_1) \geq 1$,

(1.13.4) T is continuous.

Then T has a fixed point.

Now we prove our main result to generalize Theorems 1.11 and 1.12.

2. MAIN RESULT

Theorem 2.1: Let (X, d) be a complete metric space and $\alpha : X \times X \rightarrow [0, \infty)$ be a function. Let f, g, S and T be self mappings on X satisfying

(2.1.1) $f(X) \subseteq T(X)$, $g(X) \subseteq S(X)$,

(2.1.2) $\alpha(Sx, Ty)\psi(d(fx, gy)) \leq \beta(\psi(M(x, y)))\psi(M(x, y))$ for all $x, y \in X$

where $\beta \in \mathcal{F}$, $\psi \in \Psi$ and

$$M(x, y) = \max\left\{d(Sx, Ty), d(Sx, fx), d(Ty, gy), \frac{1}{2}[d(Sx, gy) + d(Ty, fx)]\right\},$$

(2.1.3) the pairs (f, S) and (g, T) are compatible and S and T are continuous on X ,

(2.1.4) (f, g) is triangular α – admissible w.r.to (S, T) ,

(2.1.5) $\alpha(Sx_1, fx_1) \geq 1$ and $\alpha(fx_1, Sx_1) \geq 1$ for some $x_1 \in X$,

(2.1.6) Assume that $\alpha(Sy_{2n}, y_{2n-1}) \geq 1$, $\alpha(y_{2n}, Ty_{2n+1}) \geq 1$, $\alpha(z, y_{2n-1}) \geq 1$ and $\alpha(z, z) \geq 1$ whenever there exists a sequence

$\{y_n\}$ in X such that $\alpha(y_n, y_{n+1}) \geq 1$ for $n = 1, 2, 3, \dots$ and $y_n \rightarrow z$ for some $z \in X$.

Then f, g, S and T have a common fixed point.

(2.1.7) Further if $\alpha(u, v) \geq 1$ whenever u and v are common fixed points of f, g, S and T then f, g, S and T have unique common fixed point in X .

Proof: From (2.1.5), we have $\alpha(Sx_1, fx_1) \geq 1$ for some $x_1 \in X$.

From (2.1.1), define the sequences $\{x_n\}$ and $\{y_n\}$ as follows :

$$y_1 = fx_1 = Tx_2, y_2 = gx_2 = Sx_3, y_3 = fx_3 = Tx_4, y_4 = gx_4 = Sx_5, \dots$$

$$y_{2n+1} = fx_{2n+1} = Tx_{2n+2}, y_{2n+2} = gx_{2n+2} = Sx_{2n+3}, n = 0, 1, 2, \dots$$

Now

$$\begin{aligned} \alpha(Sx_1, fx_1) \geq 1 &\Rightarrow \alpha(Sx_1, Tx_2) \geq 1 \\ &\Rightarrow \alpha(fx_1, gx_2) \geq 1, \text{ from (2.1.4), i.e } \alpha(y_1, y_2) \geq 1 \\ &\Rightarrow \alpha(Tx_2, Sx_3) \geq 1 \\ &\Rightarrow \alpha(gx_2, fx_3) \geq 1, \text{ from (2.1.4), i.e } \alpha(y_2, y_3) \geq 1 \\ &\Rightarrow \alpha(Sx_3, Tx_4) \geq 1 \\ &\Rightarrow \alpha(fx_3, gx_4) \geq 1, \text{ from (2.1.4), i.e } \alpha(y_3, y_4) \geq 1 \end{aligned}$$

Continuing in this way, we have

$$\alpha(y_n, y_{n+1}) \geq 1 \text{ for } n = 1, 2, 3, \dots \tag{1}$$

Similarly using $\alpha(fx_1, Sx_1) \geq 1$, we have $\alpha(y_{n+1}, y_n) \geq 1$ for $n=1, 2, \dots$ (1)¹

By (2.1.4), using triangular property, we have

$$\alpha(y_m, y_n) \geq 1 \text{ for } m < n. \tag{2}$$

Case-(a): Suppose $y_{2m} = y_{2m+1}$.

Then $\alpha(Sx_{2m+1}, Tx_{2m+2}) = \alpha(y_{2m}, y_{2m+1}) \geq 1$ from (1).

Now

$$\begin{aligned} \psi(d(y_{2m+1}, y_{2m+2})) &= \psi(d(fx_{2m+1}, gx_{2m+2})) \\ &\leq \alpha(Sx_{2m+1}, Tx_{2m+2}) \psi(d(fx_{2m+1}, gx_{2m+2})) \\ &\leq \beta(\psi(M(x_{2m+1}, x_{2m+2}))) \psi(M(x_{2m+1}, x_{2m+2})), \end{aligned}$$

where

$$\begin{aligned} M(x_{2m+1}, x_{2m+2}) &= \max \left\{ \begin{array}{l} d(y_{2m}, y_{2m+1}), d(y_{2m}, y_{2m+1}), d(y_{2m+1}, y_{2m+2}), \\ \frac{1}{2} [d(y_{2m}, y_{2m+2}) + d(y_{2m+1}, y_{2m+1})] \end{array} \right\} \\ &= d(y_{2m+1}, y_{2m+2}) \end{aligned}$$

Thus $\psi(d(y_{2m+1}, y_{2m+2})) \leq \beta(\psi(d(y_{2m+1}, y_{2m+2}))) \psi(d(y_{2m+1}, y_{2m+2}))$

Hence

$$\begin{aligned} [1 - \beta(\psi(d(y_{2m+1}, y_{2m+2})))] \psi(d(y_{2m+1}, y_{2m+2})) &\leq 0 \text{ which in turn yields that} \\ \psi(d(y_{2m+1}, y_{2m+2})) &= 0 \text{ so that } y_{2m+1} = y_{2m+2}. \end{aligned}$$

Continuing in this way we get $y_{2m} = y_{2m+1} = y_{2m+2} = \dots$

Hence $\{y_n\}$ is Cauchy.

Case-(b): Suppose $y_n \neq y_{n+1}$ for all n .

As in Case (a), we have

$$\psi(d(y_{2n+1}, y_{2n+2})) \leq \beta(\psi(M(x_{2n+1}, x_{2n+2}))) \psi(M(x_{2n+1}, x_{2n+2})) \tag{3}$$

where

$$M(x_{2n+1}, x_{2n+2}) = \max\{d(y_{2n}, y_{2n+1}), d(y_{2n+1}, y_{2n+2})\}$$

If $M(x_{2n+1}, x_{2n+2}) = d(y_{2n+1}, y_{2n+2})$ then we get

$$\begin{aligned} \psi(d(y_{2n+1}, y_{2n+2})) &\leq \beta(\psi(d(y_{2n+1}, y_{2n+2})))\psi(d(y_{2n+1}, y_{2n+2})) \\ &< \psi(d(y_{2n+1}, y_{2n+2})) \end{aligned}$$

It is a contradiction. Hence

$$\begin{aligned} \psi(d(y_{2n+1}, y_{2n+2})) &\leq \beta(\psi(d(y_{2n}, y_{2n+1})))\psi(d(y_{2n}, y_{2n+1})) \\ &< \psi(d(y_{2n}, y_{2n+1})) \end{aligned}$$

which in turn yields that $d(y_{2n+1}, y_{2n+2}) < d(y_{2n}, y_{2n+1})$.

Similarly using (2.1.2) and (1)¹, we can show that $d(y_{2n}, y_{2n+1}) < d(y_{2n-1}, y_{2n})$.

Thus $\{d(y_n, y_{n+1})\}$ is a decreasing sequence of non-negative real numbers.

Hence it converges to some real number $r \geq 0$ such that

$$\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = r.$$

Suppose $r > 0$.

$$\text{From (3), } \frac{\psi(d(y_{2n+1}, y_{2n+2}))}{\psi(M(x_{2n+1}, x_{2n+2}))} \leq \beta(\psi(M(x_{2n+1}, x_{2n+2}))) < 1.$$

Letting $n \rightarrow \infty$ and using the continuity of ψ , we get

$$1 \leq \lim_{n \rightarrow \infty} \beta(\psi(M(x_{2n+1}, x_{2n+2}))) \leq 1$$

so that $\lim_{n \rightarrow \infty} \psi(M(x_{2n+1}, x_{2n+2})) = 0$ which in turn yields that $\psi(r) = 0$ and hence $r = 0$.

It is a contradiction. Thus

$$\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0 \tag{4}$$

Now we prove that $\{y_n\}$ is a Cauchy sequence. In view of (4), it is sufficient to show that $\{y_{2n}\}$ is Cauchy.

Assume on the contrary that $\{y_{2n}\}$ is not a Cauchy sequence. Then there exists $\epsilon > 0$ for which we can find two subsequences $\{y_{2m_k}\}$ and $\{y_{2n_k}\}$ of $\{y_{2n}\}$ so that n_k is the smallest positive integer such that $2n_k > 2m_k > k$,

$$d(y_{2m_k}, y_{2n_k}) \geq \epsilon \tag{5}$$

$$d(y_{2m_k}, y_{2n_k-2}) < \epsilon \tag{6}$$

Now from (5) and (6), we have

$$\begin{aligned} \epsilon &\leq d(y_{2m_k}, y_{2n_k}) \leq d(y_{2m_k}, y_{2n_k-2}) + d(y_{2n_k-2}, y_{2n_k-1}) + d(y_{2n_k-1}, y_{2n_k}) \\ &< \epsilon + d(y_{2n_k-2}, y_{2n_k-1}) + d(y_{2n_k-1}, y_{2n_k}) \end{aligned}$$

Letting $k \rightarrow \infty$ and using (4), we get $\epsilon \leq \lim_{k \rightarrow \infty} d(y_{2m_k}, y_{2n_k}) \leq \epsilon$ so that

$$\lim_{k \rightarrow \infty} d(y_{2m_k}, y_{2n_k}) = \epsilon \tag{7}$$

We have $\left| d(y_{2m_k+1}, y_{2n_k}) - d(y_{2m_k}, y_{2n_k}) \right| \leq d(y_{2m_k+1}, y_{2m_k})$

Letting $k \rightarrow \infty$ and using (4) and (7), we get

$$\lim_{k \rightarrow \infty} d(y_{2m_k+1}, y_{2n_k}) = \epsilon \tag{8}$$

We have $\left| d(y_{2m_k}, y_{2n_k-1}) - d(y_{2m_k}, y_{2n_k}) \right| \leq d(y_{2n_k-1}, y_{2n_k})$

Letting $k \rightarrow \infty$ and using (4) and (7), we get

$$\lim_{k \rightarrow \infty} d(y_{2m_k}, y_{2n_k-1}) = \epsilon \tag{9}$$

We have $\left| d(y_{2n_k-1}, y_{2m_k+1}) - d(y_{2m_k}, y_{2n_k}) \right| \leq d(y_{2n_k-1}, y_{2n_k}) + d(y_{2m_k}, y_{2m_k+1})$

Letting $k \rightarrow \infty$ and using (4) and (7), we get

$$\lim_{k \rightarrow \infty} d(y_{2n_k-1}, y_{2m_k+1}) = \epsilon \tag{10}$$

$$\alpha(Sx_{2m_k+1}, Tx_{2n_k}) = \alpha(y_{2m_k}, y_{2n_k-1}) \geq 1 \text{ from (2)}$$

$$\begin{aligned} \psi(d(y_{2m_k+1}, y_{2n_k})) &= \psi(d(fx_{2m_k+1}, gx_{2n_k})) \\ &\leq \alpha(Sx_{2m_k+1}, Tx_{2n_k}) \psi(d(fx_{2m_k+1}, gx_{2n_k})) \\ &\leq \beta(\psi(M(x_{2m_k+1}, x_{2n_k}))) \psi(M(x_{2m_k+1}, x_{2n_k})) \end{aligned}$$

where

$$M(x_{2m_k+1}, x_{2n_k}) = \max \left\{ \begin{aligned} &d(y_{2m_k}, y_{2n_k-1}), d(y_{2m_k}, y_{2m_k+1}), d(y_{2n_k-1}, y_{2n_k}), \\ &\frac{1}{2} [d(y_{2m_k}, y_{2n_k}) + d(y_{2n_k-1}, y_{2m_k+1})] \end{aligned} \right\}$$

$\rightarrow \epsilon$ as $k \rightarrow \infty$, from (9), (4), (7), (10).

From (11), we get

$$\frac{\psi(d(y_{2m_k+1}, y_{2n_k}))}{\psi(M(x_{2m_k+1}, x_{2n_k}))} \leq \beta(\psi(M(x_{2m_k+1}, x_{2n_k}))) < 1.$$

Letting $k \rightarrow \infty$ and using (8) and the continuity of ψ , we get

$$1 \leq \lim_{k \rightarrow \infty} \beta(\psi(M(x_{2m_k+1}, x_{2n_k}))) \leq 1$$

so that $\lim_{k \rightarrow \infty} \psi(M(x_{2m_k+1}, x_{2n_k})) = 0$ and hence $\psi(\epsilon) = 0$. Thus $\epsilon = 0$.

It is a contradiction.

Hence $\{y_{2n}\}$ is a Cauchy sequence. From (4), $\{y_{2n+1}\}$ is also Cauchy.

Since X is complete, there exists $z \in X$ such that $y_n \rightarrow z$ and hence

$$\lim_{n \rightarrow \infty} fx_{2n+1} = \lim_{n \rightarrow \infty} Tx_{2n+2} = \lim_{n \rightarrow \infty} gx_{2n+2} = \lim_{n \rightarrow \infty} Sx_{2n+1} = z.$$

Since S is Continuous, we have

$$\lim_{n \rightarrow \infty} S^2x_{2n+1} = Sz \text{ and } \lim_{n \rightarrow \infty} Sfx_{2n+1} = Sz.$$

Since the pair (f, S) is compatible, we have $\lim_{n \rightarrow \infty} d(fSx_{2n+1}, Sfx_{2n+1}) = 0$.

Hence $\lim_{n \rightarrow \infty} fSx_{2n+1} = Sz$.

Now

$$\begin{aligned} \alpha(SSx_{2n+1}, Tx_{2n}) &= \alpha(Sy_{2n}, y_{2n-1}) \geq 1 \quad \text{from (2.1.6)} \\ \psi(d(fSx_{2n+1}, gx_{2n})) &\leq \alpha(SSx_{2n+1}, Tx_{2n})\psi(d(fSx_{2n+1}, gx_{2n})) \\ &\leq \beta(\psi(M(Sx_{2n+1}, x_{2n})))\psi(M(Sx_{2n+1}, x_{2n})), \end{aligned}$$

where

$$\begin{aligned} M(Sx_{2n+1}, x_{2n}) &= \max \left\{ \begin{aligned} &d(SSx_{2n+1}, Tx_{2n}), d(SSx_{2n+1}, fSx_{2n+1}), d(Tx_{2n}, gx_{2n}), \\ &\frac{1}{2} [d(SSx_{2n+1}, gx_{2n}) + d(Tx_{2n}, fSx_{2n+1})] \end{aligned} \right\} \\ &\rightarrow d(Sz, z) \text{ as } n \rightarrow \infty. \end{aligned}$$

From (12), we get

$$\frac{\psi(d(fSx_{2n+1}, gx_{2n}))}{\psi(M(Sx_{2n+1}, x_{2n}))} \leq \beta(\psi(M(Sx_{2n+1}, x_{2n}))) < 1.$$

Letting $n \rightarrow \infty$ and using the continuity of ψ , we get

$$1 \leq \lim_{n \rightarrow \infty} \beta(\psi(M(Sx_{2n+1}, x_{2n}))) \leq 1$$

which in turn yields that $\lim_{n \rightarrow \infty} \psi(M(Sx_{2n+1}, x_{2n})) = 0$ so that $\psi(d(Sz, z)) = 0$. Hence $Sz = z$.

Since T is continuous, we have

$$\lim_{n \rightarrow \infty} T^2x_{2n+2} = Tz \text{ and } \lim_{n \rightarrow \infty} Tgx_{2n+2} = Tz.$$

Since the pair (g, T) is compatible, we have $\lim_{n \rightarrow \infty} d(Tgx_{2n+2}, gTx_{2n+2}) = 0$.

Hence $\lim_{n \rightarrow \infty} gTx_{2n+2} = Tz$.

Now

$$\begin{aligned} \alpha(Sx_{2n+1}, TTx_{2n+2}) &= \alpha(y_{2n}, Ty_{2n+1}) \geq 1 \quad \text{from (2.1.6)} \\ \psi(d(fx_{2n+1}, gTx_{2n+2})) &\leq \alpha(Sx_{2n+1}, TTx_{2n+2})\psi(d(fx_{2n+1}, gTx_{2n+2})) \\ &\leq \beta(\psi(M(x_{2n+1}, Tx_{2n+2})))\psi(M(x_{2n+1}, Tx_{2n+2})) \end{aligned} \tag{13}$$

where

$$\begin{aligned} M(x_{2n+1}, Tx_{2n+2}) &= \max \left\{ \begin{aligned} &d(Sx_{2n+1}, TTx_{2n+2}), d(Sx_{2n+1}, fx_{2n+1}), d(TTx_{2n+2}, gTx_{2n+2}), \\ &\frac{1}{2} [d(Sx_{2n+1}, gTx_{2n+2}) + d(TTx_{2n+2}, fx_{2n+1})] \end{aligned} \right\} \\ &\rightarrow d(z, Tz) \text{ as } n \rightarrow \infty. \end{aligned}$$

From (13), we get

$$\frac{\psi(d(fx_{2n+1}, gTx_{2n+2}))}{\psi(M(x_{2n+1}, Tx_{2n+2}))} \leq \beta(\psi(M(x_{2n+1}, Tx_{2n+2}))) < 1.$$

Letting $n \rightarrow \infty$ and using the continuity of ψ , we get

$$1 \leq \lim_{n \rightarrow \infty} \beta(\psi(M(x_{2n+1}, Tx_{2n+2}))) \leq 1$$

which in turn yields that $\lim_{n \rightarrow \infty} \psi(M(x_{2n+1}, Tx_{2n+2})) = 0$ so that $\psi(d(z, Tz)) = 0$. Hence $Tz = z$.

Now

$$\begin{aligned} \alpha(Sz, Tx_{2n}) &= \alpha(z, y_{2n-1}) \geq 1 && \text{from (2.1.6)} \\ \psi(d(fz, gx_{2n})) &\leq \alpha(Sz, Tx_{2n})\psi(d(fz, gx_{2n})) \\ &\leq \beta(\psi(M(z, x_{2n})))\psi(M(z, x_{2n})), \end{aligned} \tag{14}$$

where

$$\begin{aligned} M(z, x_{2n}) &= \max \left\{ \begin{aligned} &d(Sz, Tx_{2n}), d(Sz, fz), d(Tx_{2n}, gx_{2n}), \\ &\frac{1}{2}[d(Sz, gx_{2n}) + d(Tx_{2n}, fz)] \end{aligned} \right\} \\ &\rightarrow d(z, fz) \text{ as } n \rightarrow \infty. \\ \frac{\psi(d(fz, gx_{2n}))}{\psi(M(z, x_{2n}))} &\leq \beta(\psi(M(z, x_{2n}))) < 1. \end{aligned}$$

Letting $n \rightarrow \infty$ and using the continuity of ψ , we get

$$1 \leq \lim_{n \rightarrow \infty} \beta(\psi(M(z, x_{2n}))) \leq 1$$

which in turn yields that $\lim_{n \rightarrow \infty} \psi(M(z, x_{2n})) = 0$ so that $\psi(d(z, fz)) = 0$. Hence $fz = z$.

Now

$$\begin{aligned} \alpha(Sz, Tz) &= \alpha(z, z) \geq 1 && \text{from (2.1.6)} \\ \psi(d(z, gz)) &= \psi(d(fz, gz)) \\ &\leq \alpha(Sz, Tz)\psi(d(fz, gz)) \\ &\leq \beta(\psi(M(z, z)))\psi(M(z, z)), \end{aligned} \tag{15}$$

where

$$\begin{aligned} M(z, z) &= \max \left\{ \begin{aligned} &d(Sz, Tz), d(Sz, fz), d(Tz, gz), \\ &\frac{1}{2}[d(Sz, gz) + d(Tz, fz)] \end{aligned} \right\} \\ &\rightarrow d(z, gz) \text{ as } n \rightarrow \infty. \end{aligned}$$

From (15), we have

$$[1 - \beta(\psi(M(z, z)))]\psi(M(z, z)) \leq 0$$

which in turn yields that $\psi(M(z, z)) = 0$.

Thus $gz = z$.

Hence z is a common fixed point of f, g, S and T

Suppose u and v are two common fixed points of f, g, S and T

Then $\alpha(Su, Tv) = \alpha(u, v) \geq 1$ from (2.1.7)

$$\begin{aligned} \psi(d(u, v)) &= \psi(d(fu, gv)) \\ &\leq \alpha(Su, Tv)\psi(d(fu, gv)) \\ &\leq \beta(\psi(M(u, v)))\psi(M(u, v)), \end{aligned} \tag{16}$$

where

$$\begin{aligned} M(u, v) &= \max \left\{ d(u, v), d(u, u), d(v, v), \frac{1}{2}[d(u, v) + d(v, u)] \right\} \\ &= d(u, v). \end{aligned}$$

From (16), we have

$$[1 - \beta(\psi(d(u, v)))]\psi(d(u, v)) \leq 0$$

which in turn yields that so that $\psi(d(u, v)) = 0$. Hence $u = v$.

Thus f, g, S and T have a unique common fixed point.

Now, we give an example to illustrate Theorem 2.1.

Example 2.2: Let $X = [0, \infty)$ be endowed with the metric $d(x, y) = |x - y|$ for all $x, y \in X$.

Define $f, g, S, T : X \rightarrow X$ by $fx = \frac{x}{18}$, $Sx = \frac{x}{2}$, $gx = \frac{x^2}{27}$ and $Tx = \frac{x^2}{3}$ for all $x, y \in X$.

Define $\alpha : X \times X \rightarrow [0, \infty)$ by $\alpha(x, y) = \begin{cases} 1, & \text{if } x, y \in [0, 1] \\ 0, & \text{otherwise} \end{cases}$

Define $\psi : [0, \infty) \rightarrow [0, \infty)$ by $\psi(t) = \frac{t}{2}$ for all $t \in [0, \infty)$ and $\beta : [0, \infty) \rightarrow [0, 1)$ by

$$\beta(t) = \frac{1}{9} \text{ for all } t \in [0, \infty).$$

Clearly the conditions (2.1.1), (2.1.3), (2.1.4) and condition (2.1.5) with $x_1 = 0$ are satisfied.

If $Sx = \frac{x}{2} \in [0, 1]$ and $Ty = \frac{y^2}{3} \in [0, 1]$ then $\alpha(Sx, Ty) = 1$.

$$\begin{aligned} \alpha(Sx, Ty)\psi(d(fx, gy)) &= \frac{1}{2} \left| \frac{x}{18} - \frac{y^2}{27} \right| \\ &= \frac{1}{9} \left| \frac{x}{4} - \frac{y^2}{6} \right| \\ &= \frac{1}{9} \psi(d(Sx, Ty)) \\ &\leq \frac{1}{9} \psi(M(x, y)) \\ &= \beta(\psi(M(x, y)))\psi(M(x, y)) \end{aligned}$$

If $Sx = \frac{x}{2} \notin [0, 1]$ or $Ty = \frac{y^2}{3} \notin [0, 1]$ then $\alpha(Sx, Ty) = 0$.

Thus (2.1.2) is satisfied.

Clearly (2.1.6) is satisfied if we take $y_n = \frac{1}{n}$ for all n . Clearly '0' is a common fixed point of f, g, S and T .

The condition (2.1.7) is clear and '0' is unique common fixed point of f, g, S and T .

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