# A COMMON FIXED POINT THEOREM FOR SIX MAPPINGS 

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ABSTRACT
$\boldsymbol{U}$ sing notion of compatibility, weak compatibility and commutatively we have generalized fixed point theorem for six mappings satisfying rational inequality.

## 1. INTRODUCTION AND PRELIMINARIES

The concept of common fixed point theorem for commuting mapping was given by Jungck [4]. The notion of weak commutativity was introduced by Sessa [6]. Imdad and Khan [5] has proved a common fixed point theorem for six mappings which was extension of Fisher [1] and Jeong- Rhoades [3].

Definition: 1.1 [6]: A pair of self-mapping $(A, B)$ on a metric space $(X, d)$ is said to be weakly commuting if $d(A B x$, $B A x) \leq d(B x, A x)$ for all $x$ in X . Obviously, commuting mappings are weakly commuting but the converse is not necessarily true.

Definition 1.2[4]: A pair of self mappings $(A, B)$ of a metric space $(X, d)$ is said to be compatible if
$\lim _{n \rightarrow \infty} A x_{n}=\lim _{n \rightarrow \infty} B x_{n}=t \in X$. Obviously, weakly commuting mappings are compatible but the converse is not necessarily true.

The following theorem is given by Fisher [1]
Theorem 1.1: Let S and T be tow self mappings of a complete metric space $(X, d)$ such that for all $x, y$ in $X$ either
(a) $d(S x, T y) \leq \frac{b[d(x, T y)]^{2}+c[d(y, S x)]^{2}}{d(x, T y)+d(y, S x)}$

If $d(x, T y)+d(y, S x) \neq 0,0 \leq b, c, b+c<1$ or
(b) $d(S x, T y)=0$ if $d(x, T y)+d(y, S x)=0$

If one of S or T is continuous than S and T have a unique common fixed point.
Motivated by Fisher [2] and imdad and khan [5], in the present paper, an extension of theorem 1.1 is generalized for power $n$ by improving the contraction condition and choosing suitable weak commutativity conditions.

## 2 MAIN RESULT

We prove the following
Theorem 2.1: Let A, B; S, T, I and J be self mappings of a complete metric space $(X, d)$ satisfying $A B(X) \subset J(X)$, $\mathrm{ST}(\mathrm{X}) \subset \mathrm{I}(\mathrm{X})$ and for each $x$, y $\in \mathrm{X}$ either

$$
\begin{align*}
d(A B x, S T y) \leq \alpha_{1} & {\left[\frac{[d(A B x, J y)]^{n}+[d(S T y, I x)]^{n}}{[d(A B x, J y)]^{n-1}+[d(S T y, I x)]^{n-1}}\right] }  \tag{2.1}\\
& +\alpha_{2}[d(A B x, I x)+d(S T y, J y)]+\alpha_{3} d(I x, J y)
\end{align*}
$$

ifd $(A B x, J y)^{n-1}+d(S T y, I x)^{n-1} \neq 0, \alpha_{i} \geq, 0 \quad(\mathrm{i}=1,2,3)$ with atleast one $\alpha_{i}$ non zero and
$2 \alpha_{1}+2 \alpha_{2}+\alpha_{3}<1$ or $d(A B x$, STy $)=0$ if $[d(A B x, J y)]^{n-1}+[d(S T y, I x)]^{n-1}=0$
If either
(i) $\{\mathrm{AB}, \mathrm{I}\}$ are compatible, I or AB is continuous and ( $\mathrm{ST}, \mathrm{J}$ ) are weakly compatible, or
(ii) $\{\mathrm{ST}, \mathrm{J}\}$ are compatible, J or ST is continuous and ( $\mathrm{AB}, \mathrm{I}$ ) are weakly compatible then $\mathrm{AB}, \mathrm{ST}, \mathrm{I}$ and J have a unique common fixed point. Furthermore if the pairs (A, B), (A, I), (B, I), (S, T), (S, J), (T, J) are commuting mappings then A, B, S, T, I and J have a unique common fixed point.'"

Proof: Let $x_{0}$ be an arbitrary point in X . Since $\mathrm{AB}(\mathrm{X}) \subset \mathrm{J}(\mathrm{X})$ we can find a point $x_{1}$ in X such that $\mathrm{AB} x_{0}=\mathrm{J} x_{1}$. Also since $\mathrm{ST}(\mathrm{X})$ subset of $\mathrm{I}(\mathrm{X})$ we can choose a point $x_{2}$ with $\mathrm{ST} x_{1}=\mathrm{I} x_{2}$. Using this argument repeatedly one can construct a sequence $\left\{\mathrm{z}_{\mathrm{n}}\right\}$ such that $\mathrm{Z}_{2 \mathrm{n}}=\mathrm{AB} x_{2 \mathrm{n}}=\mathrm{J} x_{2 n+1}, \mathrm{Z}_{2 \mathrm{n}+1}=\mathrm{ST} x_{2 n+1}=\mathrm{I} x_{2 n+2}$ for $\mathrm{n}=0,1,2 \ldots$.

For brevity let us put
$\mathrm{u}_{2 \mathrm{n}}=\mathrm{d}\left(\mathrm{AB} x_{2 \mathrm{n}}, \mathrm{ST} x_{2_{2 n+1}}\right)$ and $\mathrm{u}_{2 \mathrm{n}+1}=\mathrm{d}\left(\mathrm{ST} x_{2 n+1}, \mathrm{AB} x_{2 n+2}\right)$ for $\mathrm{n}=0,1,2 \ldots \ldots$. Now we distinguish two cases:
(i) Suppose that $\mathrm{u}_{2 \mathrm{n}}+\mathrm{u}_{2 \mathrm{nn+1}} \neq 0$ for $\mathrm{n}=0,1,2 \ldots \ldots$

Then using the inequality (2.1.1), we have

$$
\begin{aligned}
\mathrm{u}_{2 n+1}=d\left(z_{2 n+1}, z_{2 n+2}\right)= & d\left(S T x_{2 n+1}, A B x_{2 n+2}\right) \\
\leq & \alpha_{1}\left[\frac{\left[d\left(A B x_{2 n+1}, J x_{2 n+1}\right)\right]^{n}+\left[d\left(S T x_{2 n+1}, I x_{2 n+1}\right)\right]^{n}}{\left[d\left(A B x_{2 n+2}, J x_{2 n+1}\right)\right]^{n-1}+\left[d\left(S T x_{2 n+1}, I x_{2 n+2}\right)\right]^{n-1}}\right] \\
& +\alpha_{2}\left[d\left(A B x_{2 n+1}, I x_{2 n+2}\right)+d\left(S T x_{2 n+1}, J y_{2 n+2}\right)\right]+\alpha_{3} d\left(I x_{2 n+2}, J y_{2 n+1}\right) \\
\text { or } \quad d\left(z_{2 n+1}, z_{2 n+2}\right) \leq & \frac{\alpha_{1}+\alpha_{2}+\alpha_{3}}{1-\alpha_{1}-\alpha_{2}} d\left(z_{2 n}, z_{2 n+1}\right)
\end{aligned}
$$

Similarly we can show that
$d\left(z_{2 n}, z_{2 n+1}\right) \leq \frac{\alpha_{1}+\alpha_{2}+\alpha_{3}}{1-\alpha_{1}-\alpha_{2}} d\left(z_{2 n-1}, z_{2 n}\right)$
thus for every $n$ we have $d\left(z_{n}, z_{n+1}\right) \leq k d\left(z_{n-1}, z_{n}\right)$
which shows that $\left\{z_{n}\right\}$ is a cauchy sequence in the complete metric space ( $\mathrm{X}, \mathrm{d}$ ) and so has a limit point $z$ in X . hence the sequence $\mathrm{AB} x_{2 \mathrm{n}}=\mathrm{J} x_{2 n+1}$ and $\mathrm{ST} x_{2 n+1}=\mathrm{J} x_{2 n+2}$ which are subsequences also converge to the point $z$.
let us now assume that $I$ is continuous so that the sequence $\left\{I^{2} x_{2 n}\right\}$ and $\left\{I A B x_{2 n}\right\}$ converges to $I z$. Also in view of compatibility of $\{I, A B\},\left\{A B I x_{2 n}\right\}$ converges to $I z$.

$$
\begin{aligned}
d\left(A B I x_{2 n}, S T x_{2 n+1}\right) \leq \alpha_{1} & {\left[\frac{\left[d\left(A B I x_{2 n}, J x_{2 n+1}\right)\right]^{n}+\left[d\left(S T x_{2 n+1}, I^{2} x_{2 n}\right)\right]^{n}}{\left[d\left(A B I x_{2 n}, J x_{2 n+1}\right)\right]^{n-1}+\left[d\left(S T x_{2 n+1}, I^{2} x_{2 n}\right)\right]^{n-1}}\right] } \\
& +\alpha_{2}\left[d(A B z, I z)+d\left(S T x_{2 n+1}, J x_{2 n+1}\right)+\alpha_{3}\left[d\left(I z, J x_{n+1}\right)\right]\right]
\end{aligned}
$$

Which on letting $n \rightarrow \infty$ reduces to $\left(1-\alpha_{1}-\alpha_{3}\right) d(I z, z) \leq 0$
yielding thereby $I z=z$
Now,

$$
\begin{aligned}
d\left(A B z, S T x_{2 n+1}\right) \leq \alpha_{1}[ & {\left[\frac{\left[d\left(A B z, J x_{2 n+1}\right)\right]^{n}+\left[d\left(S T x_{2 n+1}, I z\right)\right]^{n}}{\left[d\left(A B z, J x_{2 n+1}\right)\right]^{n-1}+\left[d\left(S T x_{2 n+1}, I z\right)\right]^{n-1}}\right] } \\
& +\alpha_{2}\left[d(A B z, I z)+d\left(S T x_{2 n+1}, J x_{2 n+1}\right)\right]+\alpha_{3}\left[d\left(I z, J x_{n+1}\right)\right]
\end{aligned}
$$

On letting and using $I z=z \quad$ we get
$d(A B z, z) \leq\left(\alpha_{1}+\alpha_{2}\right) d(A B z, z)$

This implies $A B z=z$
Since $\quad A B(x) \subset J(x)$ then there always exists a point $z^{\prime}$ such that
$J z^{\prime}=z$ so that $S T z=S T\left(J z^{\prime}\right)$

Now

$$
\begin{aligned}
d(z, S T z) & =d(A B z, S T z) \\
& \leq \alpha_{1}\left[\frac{\left[d\left(A B z, J z^{\prime}\right)\right]^{n}+\left[d\left(S T z^{\prime}, I z\right)^{n}\right.}{\alpha\left(A B z, J z^{\prime}\right)^{n-1}+d\left(S T z^{\prime}, I z\right)^{n-1}}\right]+\alpha_{2}\left[d(A B z, I z)+d\left(S T z^{\prime}, J z z^{\prime}\right)\right]+\alpha_{3} d\left(I z, J z^{\prime}\right) \\
& \leq\left(\alpha_{1}+\alpha_{2}\right)\left[d\left(S T z^{\prime}, z\right)\right]
\end{aligned}
$$

Hence, $S T z^{\prime}=z=J z^{\prime}$ which shows that $z^{\prime}$ is a common point of $A B, I, S T$ and $J$. Now using the weak compatibility of $(S T, J)$, we have $S T z=S T\left(J z^{\prime}\right)=J\left(S T z^{\prime}\right)=J z$ which shows that $z$ is also a coincidence point of the pair (ST, J). Now

$$
\begin{aligned}
d(z, S T z) & =d(A B z, S T z) \\
& \leq \alpha_{1}\left[\frac{[d(A B z, J z)]^{n}+[d(S T z, I z)]^{n}}{\alpha(A B z, J z)^{n-1}+d(S T z, I z)^{n-1}}\right]+\alpha_{2}[d(A B z, I z)+d(S T z, J z)]+\alpha_{3} d(I z, J z) \\
& \leq\left(\alpha_{1}+\alpha_{3}\right) d(z, S T z)
\end{aligned}
$$

Hence $z=S T z=J z$ which shows that $z$ is a common fined point of $A B, I, S T$ and $J$.
Now suppose that $A B$ is continuous so that the sequences $\left\{A B^{2} x_{2 n}\right\}$ and $\left\{A B I x_{2 n}\right\}$ converge to $A B z$, since $(A B, I)$ are compatible it follows that $\left\{I A B x_{2 n}\right\}$ also converge to $A B z$, thus

$$
\begin{aligned}
d\left(A B^{2} x_{2 n}, S T x_{2 n+1}\right) \leq \alpha_{1} & {\left[\frac{\left[d\left(A B^{2} x_{2 n}, J x_{2 n+1}\right)\right]^{n}+\left[d\left(S T x_{2 n+1}, \operatorname{IAB} x_{2 n}\right)\right]^{n}}{\left[d\left(A B^{2} x_{2 n}, J x_{2 n+1}\right)\right]^{n-1}+\left[d\left(S T x_{2 n+1}, \operatorname{IABx} x_{2 n}\right)\right]^{n-1}}\right] } \\
& +\alpha_{2}\left[d\left(A B^{2} x_{2 n}, I A B x_{2 n}\right)+d\left(S T x_{2 n+1}, J x_{2 n+1}\right)\right]+\alpha_{3} d\left(I_{A B x_{2 n}}, J x_{2 n+1}\right)
\end{aligned}
$$

which on letting $n \rightarrow \infty$ reduces to
$d(A B z, z) \leq\left(\alpha_{1}+\alpha_{3}\right) d(A B z, z)$
which implies $A B z=z$ as earlier, there exists $z^{\prime}$ is $X$ such that
$A B z=z=J z^{\prime}$ then

$$
\begin{aligned}
d\left(A B^{2} x_{2 n}, S T z^{\prime}\right) \leq \alpha_{1} & {\left[\frac{\left[d\left(A B^{2} x_{2 n}, J z^{\prime}\right)\right]^{n}+\left[d\left(S T z^{\prime}, I A B x_{2 n}\right)\right]^{n}}{\left[d\left(A B^{2} x_{2 n}, J z^{\prime}\right)\right]^{n-1}+\left[d\left(S T z^{\prime}, I A B x_{2 n}\right)\right]^{n-1}}\right] } \\
& +\alpha_{2}\left[d\left(A B^{2} x_{2 n}, I A B x_{2 n}\right)+d\left(S T z^{\prime}, J z^{\prime}\right)\right]+\alpha_{3} d\left(I A B x_{2 n}, J z^{\prime}\right)
\end{aligned}
$$

This on letting $n \rightarrow \infty$ reduces to
$d\left(z, S T z^{\prime}\right) \leq\left(\alpha_{1}+\alpha_{2}\right) d\left(z, S T z^{\prime}\right)$
This gives $S T z^{\prime}=z=J z^{\prime}$ thus $z^{\prime}$ is a coincidence point of $(S T, J)$. since, the pair $(S T, J)$ is weakly compatible hence $S T z=S T\left(J z^{\prime}\right)=J\left(S T z^{\prime}\right)=J z$ which shows that $S T z=J z$ further,

$$
\begin{aligned}
d\left(A B x_{2 n}, S T z\right) \leq \alpha_{1}[ & \left.\frac{\left[d\left(A B x_{2 n}, J z\right)\right]^{n}+\left[d\left(S T z, I x_{2 n}\right)\right]^{n}}{\left[d\left(A B x_{2 n}, J z\right)\right]^{n-1}+\left[d\left(S T z, I x_{2 n}\right)\right]^{n-1}}\right] \\
& +\alpha_{2}\left[d\left(A B x_{2 n}, I x_{2 n}\right)+d(S T z, J z)\right]+\alpha_{3} d\left(I x_{2 n}, J z\right)
\end{aligned}
$$

which on letting $n \rightarrow \infty$ reduces to
$d(z, S T z) \leq\left(\alpha_{1}+\alpha_{3}\right) d(z, S T z)$
$d(S T z, z)=0$
it follows that $\quad S T z=z=J z$
The point $z$ therefore is in the range of $S T$ and since $S T(X) \subset I(X)$ there exist a point $z^{\prime}$ in $X$ such that $I z^{\prime \prime}=z$ thus
$d\left(A B z^{\prime \prime}, z\right)=d\left(A B z^{\prime \prime}, S T z\right) \leq \alpha_{1} \frac{\left[d\left(A B z^{\prime \prime}, J z\right)\right]^{n}+\left[d\left(S T z, I z^{\prime \prime}\right)\right]^{n}}{\left[d\left(A B z^{\prime}, J z\right)\right]^{n-1}+\left[d\left(S T z, I z^{\prime \prime}\right)\right]^{n-1}}$

$$
+\alpha_{2}\left[d\left(A B z^{\prime}, I z "\right)+d(S T z, J z)\right]+\alpha_{3} d(I z ", J z)
$$

Letting $n \rightarrow \infty$
$d\left(A B z z^{\prime \prime} z\right) \leq\left(\alpha_{1}+\alpha_{2}\right) d\left(A B z^{\prime \prime}, z\right)$

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which shows that $A B z^{\prime \prime}=z$
Also since $(A B, I)$ are compatible and hence using weakly commuting we obtain

$$
\begin{aligned}
d(A B z, I z) & =d\left(A B\left(I z z^{\prime}\right), I\left(A B z^{\prime \prime}\right)\right) \\
& \leq d\left(I z^{\prime \prime}, A B z^{\prime \prime}\right)=d(z, z)=0
\end{aligned}
$$

Therefore $A B z=I z=z$
Thus we have proved that $z$ is common fixed point of $A B, S T, I$ and $J$.

If the mappings $S T$ or $J$ is continuous instead of $A B$ or $I$ then proof of $z$ is a common fixed point of $A B, S T, I$ and $J$ is similar.

Let $v$ be another fixed point of $I, J, A B$ and $S T$
then

$$
\begin{aligned}
d(z, v) & =d(A B z, S T v) \\
& \leq \alpha_{1}\left[\frac{[d(A B z, J v)]^{n}+[d(S T v, I z)]^{n}}{[d(A B z, J v)]^{n-1}+[d(S T v, I z)]^{n-1}}\right] \\
& +\alpha_{2}[d(A B z, I z)+d(S T v, J v)] \\
& +\alpha_{3} d(I z, J v) \\
d(z, v) & \leq\left(\alpha_{1}+\alpha_{3}\right) d(z, v) \text { yielding thereby } z=v
\end{aligned}
$$

Finally we need to show that $z$ is also a common fixed point of $A, B, S, T, I$ and $J$. For this let $z$ be the unique common fixed point of both the pairs $(A B, I)$ and $(S T, J)$. Then
$A z=A(A B z)=A(B A z)=A B(A z), A z=A(l z)=I(A z)$
$B z=B(A B z)=B(A(B z))=B A(B z)=A B(B z) . \quad B z=B(l z)=I(B z)$
which shows that $A z$ and $B z$ is a common fixed point of $(A B, I)$ yielding thereby $A z=z=B z=I z=A B z$ in the view of uniqueness of the common fixed point of the pair $(A B, I)$.

Similarly using the commutatively of $(S, T),(S J)$ and $(T, J)$ it can be shown that $S z=z=T z=J z=S T z$.

Now we need to show that $A z=S z(B z=T z)$ also remains a common fixed point of both the pairs $(A B, I)$ and $(S T, J)$. For this

$$
\begin{aligned}
d(A z, S z) & =d(A(B A z), S(T S z)) \\
& =d(A B(A z), S T(S z)) \\
& \leq \alpha_{1}\left[\frac{[d(A B(A z), J(S z))]^{n}+[d(S T(S z), I(A z))]^{n}}{[d(A B(A z), J(S z))]^{n-1}+[d(S T(S z), I(A z))]^{n-1}}\right]
\end{aligned}
$$

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+\alpha_{2}[d(A B(A z), I(A z))+d(S T(S z), J(S z))]+\alpha_{3} d(I(A z), J(S z))
$$ 

implies that $d(A z, S z)=0($ as $d(A B(A z), J(S z)+d(S T(S z), I(A z))=0)$ yielding thereby $A z=S z$.

Similarly it can be shown that $B z=T z$. Thus $z$ is the unique common fixed of $A, B, S, T, l$ and $J$.
(ii) Suppose that $d(A B x, J y)+d(S T y, l x)=0$ implies $d(A B x, S T y)=0$. Then we argue as follows.

Suppose that there exists an $n$ such that $z_{n}=z_{n+1}$. Then, also $z_{n+1}=z_{n+2}$. Suppose not. Then from (2.3) we have $0<d\left(z_{n+1}, z_{n+2}\right) \leq k d\left(z_{n+1}, z_{n}\right)$ yielding thereby $z_{n+1}=z_{n+2}$. Thus $z_{n}=z_{n+k}$ for $k=1,2, \ldots$. it then follows that there exist two point $w_{1}$ and $w_{2}$ such that $v_{1}=A B w_{1}=J w_{2}$ and $v_{2}=S T w_{2}=l w_{1}$. Since $d\left(A B w_{1}, J w_{2}\right)+d\left(S T w_{2}, I w_{1}\right)=0$ from (2.2) $d\left(A B w_{1}, S T w_{2}\right)=0$.i.e. $v_{1}=A B w_{1}=S T w_{2}=v_{2}$. Also note that $I v_{1}=I\left(A B w_{1}\right)=A B\left(I w_{1}\right)=A B v_{1}$. Similarly $S T v_{2}=J v_{2}$. Define $y_{1}=A B v_{1}, y_{2}=S T v_{2}$. Since $d\left(A B v_{1}, J v_{2}\right)+d\left(S T v_{2}, I v_{1}\right)=0$, it follow from (2.2) that $d\left(A B v_{1}, S T v_{2}\right)=0$, i.e. $y_{1}=y_{2}$. Thus $A B v_{1}=I v_{1}=S T v_{2}=J v_{2}$. But $v_{1}=v_{2}$. follows $A B, I, S T$ and $J$ have a common coincidence point. Define $w=A B v_{1}$, it then follows that $w_{\text {is }}$ also a common coincidence point of $A B, I, S T$ and $J$. If $A B w \neq A B v_{1}=S T v_{1}$, then $d\left(A B w, S T v_{1}\right)>0$. But, since $d\left(A B w, J v_{1}\right)+d\left(S T v_{1}, l w\right)=0$, it follows from (2.2) that $d\left(A B w, S T v_{1}\right)=0$, i.e. $A B w=S T v_{1}$, a contradiction. Therefore $A B w=A B v_{1}=w$ and $w$ is a common fixed point of $A B, S T, I$ and $J$.

The rest of the proof is identical to the case (1), hence it is omitted. This completes the proof.
Corollary 2.2: Theorem 2.1 remains true if contraction conditions (2.1.1) and (2.1.2) are replaced by any of the following conditions:
(i) Eitherd $(A B z, S T y) \leq \alpha_{1}\left[\frac{[d(A B x, J y)]^{n}+[d(S T y, I x)]^{n}}{[d(A B x, J y)]^{n-1}+[d(S T y, l x)]^{n-1}}\right]$
$+\alpha_{2}[d(A B x, l x)+d(S T y, J y)]$
if $d(A B x, J y)+d(S T y, l x) \neq 0, \quad \alpha_{1}, \alpha_{2}>0,2 \alpha_{1}+2 \alpha_{2}<1$ or
$d(A B x, S T y)=0$ if $d(A B x, J y)+d(S T y, l x)=0$
(ii) Either $d(A B x, S T y) \leq \alpha_{1}\left[\frac{[d(A B x, J y)]^{n}+[d(S T y, I x)]^{n}}{[d(A B x, J y)]^{n-1}+[d(S T y, l x)]^{n-1}}\right]+\alpha_{3}(l x, J y)$
if $d(A B x, J y)+d(S T y, l x) \neq 0, \quad \alpha_{1}, \alpha_{3}>0,2 \alpha_{1}+\alpha_{3}<1$ or
$d(A B x, S T y)=0$ if $d(A B x, J y)+d(S T y, l x)=0$
(iii) Eitherd $(A B x, S T y) \leq \alpha_{1}\left[\frac{[d(A B x, J y)]^{n}+[d(S T y, I x)]^{n}}{[d(A B x, J y)]^{n-1}+[d(S T y, l x)]^{n-1}}\right]$
if $d(A B x, J y)+d(S T y, l x) \neq 0, \quad \alpha_{1}>0, \alpha_{1}<1 / 2$ or
(C)
$d(A B x, S T y)=0$ if $d(A B x, J y)+d(S T y, l x)=0$
(iv) $d(A B x, S T y) \leq \alpha_{1}[d(A B x, J y)+d(S T y, J y)]$

$$
\begin{align*}
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& \qquad+\alpha_{2}[d(A B x, l x)+d(S T y, J y)]+\alpha_{3} d(l x, J y) \text { if } 2 \alpha_{1}+2 \alpha_{2}+\alpha_{3}<1
\end{aligned} \begin{aligned}
& \text { (v) } d(A B x, S T y) \leq \alpha_{1}[d(A B x, J y)+d(S T y, l x)] \text { if } \alpha_{1}<\frac{1}{2}  \tag{D}\\
& \text { (vi) } d(A B x, S T y) \leq \alpha_{2}[d(A B x, l x)+d(S T y, J y)] \text { if } \alpha_{2}<1 / 2  \tag{E}\\
& \text { (vii) } d(A B x, S T y) \leq \alpha_{3} d(l x, J y) \text { if } \alpha_{3}<1 \tag{F}
\end{align*}
$$

Proof:. Corollaries corresponding to the contraction conditions (A), (B) and (C) can be deduced directly from Theorem 2.1 by choosing $\alpha_{3}=0, \alpha_{2}=0$ and $\alpha_{2}=\alpha_{3}=0$, respectively. The corollary corresponding the contraction condition (D) also follows from Theorem 2.1 by noting that

$$
\begin{aligned}
\frac{[d(A B x, J y)]^{n}+[d(S T y, l x)]^{n}}{[d(A B x, J y)]^{n-1}+[d(S T y, l x)]^{n-1}} & \leq \frac{[d(A B x, J y)+d(S T y, l x)]^{n}}{[d(A B x, J y)+d(S T y, l x)]^{n-1}} \\
& \leq[d(A B x, J y)+d(S T y, l x)]
\end{aligned}
$$

Finally one may note that the contraction conditions (E), (F) and (G) are special cases of the contraction condition (D).

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