# THE OSSERMAN SURFACES 

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#### Abstract

A hyper surface $M \subset R^{n+1}$ is pointwise Osserman surface if the eigenvalues of the Jacobi operator $J(X)=R(u, X, X)$, where $R$ is the curvature tensor of $M$, are pointwise constants, for any tangent vector $X$ in the tangent space $M_{p}$, at any point $p \in M$. In this short note we prove that $M$ is Osserman surface if and only if $M$ is locally Euclidean hyper surface or hyper surface of constant sectional curvature.


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Keywords: Jacobi operator, hyper surface, pointwise Osserman, Weingarten operator, locally Euclidean hyper surface, hyper sphere.

Let $(N, g)$ be a Riemannian manifold with metric tensor $g$, and curvature tensor $R$, defined by the formula:

$$
R^{\prime}(X, Y)=\nabla_{X}^{\prime} Y-\nabla_{Y}^{\prime} X-\nabla_{[X, Y]},
$$

where $\nabla$ is the Levi-Civita connection on $N$, and $X, Y$ are arbitrary tangent vector fields in the tangent bundle $\mathcal{N}(N)$, on the manifold $N$.

Let $(M, g)$ be an $n$-dimensional Riemannian manifold, which is isometric embedding in ( $N, g$ ), and let $\operatorname{dim} N=n+m$. If we consider locally in a neighborhood $U_{p}$, at a point $p \in M$, then we always can choose a smooth intersections $\xi_{1}, \xi_{2}, \ldots, \xi_{m}$ in the normal bundle $\mathfrak{\aleph}(M)^{\perp}$, which are independent vector fields, and which form an orthonormal basis at any point $p \in U_{p}$. If $X, Y$ are smooth vector fields in the tangent bundle $\mathfrak{\aleph}(M)$, then

$$
\left(\nabla_{X}^{\prime} Y\right)_{p}=\left(\nabla_{X} Y\right)_{p}+\alpha(X, Y)_{p}
$$

where $\nabla_{X} Y$ is the covariant derivation, defined for the Riemannian connection $\nabla$ on the submanifold ( $M, g$ ), respectively $\alpha(X, Y)$ is the second fundamental form of $(M, g)$. Also

$$
\alpha(X, Y)=\sum_{i=1}^{m} h^{i}(X, Y) \xi_{i}
$$

is the decomposition of $\alpha(X, Y)$, with respect to the orthonormal basis $\xi_{1}, \xi_{2}, \ldots, \xi_{m} \in M_{p}$, at a point $p \in M$.
According to the definition, for any smooth vector field $\xi \in \mathfrak{\aleph}(M)^{\perp}$, holds

$$
\left(\nabla_{X}^{\prime}\right)_{p}=-\left(A_{\xi}(X)\right)_{p}+D_{\xi}(X)_{p},
$$

where $A_{\xi}$ is a linear symmetric Weingarten operator in $M_{p}$, at a point $p \in M$, such that

$$
g\left(A_{\xi}(X), Y\right)=g(\alpha(X, Y), \xi)
$$

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The following formulae and equations are well known) [3]:
I. The Gauss formula:

$$
\nabla_{X}^{\prime} Y=\nabla_{X} Y+\alpha(X, Y)
$$

II. The Weingarten formula:

$$
\left(\nabla_{X}^{\prime} \xi\right)=-A_{\xi}(X)+D_{\xi}(X)
$$

III. The Gauss equation:

$$
g\left(R^{\prime}(X, Y, Z) U\right)=g(R(X, Y, Z) U)+g(\alpha(X, Z) \alpha(Y, U))-g(\alpha(Y, Z) \alpha(X, U))
$$

where $R$ is the curvature tensor of the Riemannian manifold $(M, g)$, and where $X, Y, Z, U$ are the tangent vector fields in the tangent bundle $\mathfrak{N}(M)$.

Further we consider the case, when the Riemannian manifold $N$ coincide with Euclidean vector space $\mathrm{R}^{n+1}$, and the Riemannian submanifold $M$ is a hyper surface in $\mathrm{R}^{n+1}$. Then the Gauss equation has the form [3]:

$$
R(X, Y, Z)=g(A Y, Z) A X-g(A X, Z) A Y
$$

In the next we will use the Jacobi operator

$$
J(X)=R(u, X, X)
$$

which is a linear symmetric operator, defined for any unit tangent vector $X \in M_{p}$, at a point $p \in M$ [1], [2], [4]. Following the terminology in [2] we introduce

Definition 1: A hyper surface $M \subset \mathrm{R}^{n+1}$ is pointwise Osserman surface if the eigenvalues of the Jacobi operator $J(X)$ are pointwise constants, for any tangent vector $X \in M_{p}$, at any point $p \in M$.

Let $M$ be a pointwise Osserman hyper surface in the Euclidean vector space $\mathrm{R}^{n+1}$.
Let $A$ be the Weingarten operator in $M_{p}$, and let $X_{1}, X_{2}, \ldots, X_{n}$ be the eigenvector basis of $A$.
Let $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}$ be the eigenvalues, corresponding to the eigenvectors $X_{1}, X_{2}, \ldots, X_{n}$. Then for any indexes $I<j$ (i,j=1, 2, .., n) holds:

$$
\begin{align*}
R\left(X_{i}, X_{j}, X_{k}\right) & =g\left(A X_{j}, X_{k}\right) A X_{i}-g\left(A X_{i}, X_{k}\right) A X_{j}= \\
& =\left\{\begin{array}{cl}
0 & , \quad k \neq i, j \\
-\lambda_{i} \lambda_{j} & , \\
\lambda_{i} \lambda_{j} & , \quad k=i
\end{array}\right. \tag{1}
\end{align*}
$$

It is easy to see that the matrix of the Jacobi operator $J\left(X_{1}\right)$, with respect to the orthonormal basis $X_{1}, X_{2}, \ldots, X_{n}$, has the form:

$$
\left(J\left(X_{1}\right)\right)=\left(\begin{array}{ccccc}
\lambda_{1} \lambda_{2} & 0 & 0 & 0 & 0 \\
0 & \lambda_{1} \lambda_{3} & 0 & 0 & 0 \\
0 & 0 & \lambda_{1} \lambda_{4} & 0 & 0 \\
\ldots & \ldots & \ldots & \ldots & \ldots \\
0 & 0 & 0 & 0 & \lambda_{1} \lambda_{n}
\end{array}\right)
$$

where $J\left(X_{1}\right)$ we consider as a linear symmetric operator in the tangent subspace

$$
X_{1}^{\perp}=\operatorname{span}\left\{\left(X_{2}, X_{3}, \ldots, X_{n}\right) \subset M_{p}\right\}, p \in M
$$

Similarly we can check that the matrix of the Jacobi operator $J\left(X_{2}\right)$, with respect to the orthonormal basis $X_{1}, X_{2}, \ldots, X_{n}$, has the form:

$$
\left(J\left(X_{2}\right)\right)=\left(\begin{array}{ccccc}
\lambda_{2} \lambda_{1} & 0 & 0 & 0 & 0 \\
0 & \lambda_{2} \lambda_{3} & 0 & 0 & 0 \\
0 & 0 & \lambda_{2} \lambda_{4} & 0 & 0 \\
\ldots & \ldots & \ldots & \ldots & \ldots \\
0 & 0 & 0 & 0 & \lambda_{2} \lambda_{n}
\end{array}\right)
$$

where $J\left(X_{2}\right)$ we consider as a linear symmetric operator in the tangent subspace

$$
X_{2}^{\perp}=\operatorname{span}\left\{\left(X_{1}, X_{3}, \ldots, X_{n}\right) \subset M_{p}\right\}, p \in M
$$

From our condition $M$ to be pointwise Osserman hyper surface in $\mathrm{R}^{n+1}$, it follows that the eigenvalues $\lambda_{1} \lambda_{2}, \lambda_{1} \lambda_{3}, \ldots, \lambda_{1 n}$ and $\lambda_{2} \lambda_{1}, \lambda_{2} \lambda_{3}, \ldots, \lambda_{2 n}$ of the Jacobi operators $J\left(X_{1}\right)$ and $J\left(X_{2}\right)$ coincide, hence

$$
\begin{equation*}
\lambda_{1} \lambda_{s}=\lambda_{2} \lambda_{s}, \quad s=3,4, \ldots, n . \tag{2}
\end{equation*}
$$

From this equality it follows that at least one $\lambda_{s}=0$, for any indexes $s=3,4, \ldots, n$, and then all eigenvalues $K_{s j}(s \neq j=1,2, \ldots, n)$, of the Jacobi operator $J\left(X_{S}\right)$, are equal to 0 . Since we assume $M$ to be pointwise Osserman hyper surface in $\mathrm{R}^{n+1}$, then all eigenvalues of any Jacobi operator $J\left(X_{S}\right)(s=1,2, \ldots, n)$ are equal to 0 . That means that the matrix of the curvature operator $\Re$ on the second exterior product $\wedge^{2} M_{p}$, with respect to the orthonormal 2-vector basis $X_{S} \Lambda X_{t}(s<t, s, t=1,2, \ldots, n) \in \wedge^{2} M_{p}$, is zero matrix, which means that $\mathfrak{R} \equiv 0$. From the last equality it follows that the curvature tensor $R$ of hyper surface $M$ is vanishing, which means that $M$ is locally Euclidean hyper surface in $\mathrm{R}^{n+1}$ [3]. If all $\lambda_{s} \neq 0$, for any indexes $s=3,4, \ldots, n$ in the equalities (2), then $\lambda_{1}=\lambda_{2}$ and if these values are equal to 0 , then all eigenvalues of the Jacobi operators $J\left(X_{1}\right)$ and $J\left(X_{2}\right)$ are equal to 0 . Now from the assumption $M$ to be pointwise Osserman hyper surface in $\mathrm{R}^{n+1}$, it follows that all eigenvalues of any Jacobi operator $J\left(X_{S}\right)(s=1,2, \ldots, n)$, are equal to 0 , and then $M$ is locally Euclidean hyper surface in $\mathrm{R}^{n+1}$, again. If $\lambda_{1}=\lambda_{2} \neq 0$, then using all Jacobi operators $J\left(X_{S}\right)(s=3,4, \ldots, n)$, we get $\lambda_{1}=\lambda_{2}=\ldots=\lambda_{n} \neq 0$, which means that $M$ is hyper surface of constant sectional curvature[3]. Thus we prove

Theorem 1: $M$ is pointwise Osserman hyper surface in $\mathrm{R}^{n+1}$ if and only if one of the following cases is true:

1) $M$ is a locally Euclidean hyper surface;
2) $M$ is a hyper surface of constant sectional curvature .

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