

**TENSOR AND DUAL REPRESENTATIONS
FOR SU(2) BY THE MATRIX LIE ALGEBRAS su(2) AND sl(2)**

SAAD OWAID*, ZAINAB SUBHI

**Department of Mathematics,
College of Science, University of Al-Mustansiriyah, Baghdad- Iraq.**

(Received On: 18-04-16; Revised & Accepted On: 05-05-16)

ABSTRACT

In this work, we continue our study started in [6] on representations of the matrix lie group SU(2) resulting by conjugation action on the matrix lie algebras su(2) and sl(2). We calculate the tensor and dual representations for the obtained adjoint representations Ad₁ and Ad₂.

INTRODUCTION

In 1888, during his work at certain transformation groups, a Norwegian mathematician Sophus Lie initiated Lie theory. Later his researches led to a fundamental concept, namely, Lie algebras. Nowadays this theory becomes an indispensable for various branches in both mathematics and theoretical physics, for example, see [2] and [5]. One of the most fruitful approaches in representation theory is; choosing a group action on a vector space over a specific field; such procedure leads to a huge amount of research efforts in representation theory[1].

In [3] Helmer Aslaksen find certain summands in tensor products of Lie algebra representations. Mahmoud and his colleagues [4], constructed new representation of SU(4) in terms of Pauli matrices.

Follow the procedure that we used in [6], that is exploiting the generators of the matrix lie group SU(2) and the basis of the matrix lie algebras su(2) and sl(2), we construct tensor Ad₁ ⊗ Ad₂ and dual Ad₁[∧], Ad₂[∧] representations .

1. TENSOR PRODUCT OF REPRESENTATIONS

Recall that if \mathbb{U}, \mathbb{V} are two vector spaces over a field F of dimensions n, m , and basis $\{\ell_i\}_{i=1}^n, \{h_j\}_{j=1}^m$ respectively, then the set $\{\ell_i \otimes h_j \mid 1 \leq i \leq n, 1 \leq j \leq m\}$ form a basis for the tensor product $\mathbb{U} \otimes \mathbb{V}$ such that $\dim(\mathbb{U} \otimes \mathbb{V}) = \dim(\mathbb{U}).\dim(\mathbb{V})=n.m$.

Definition 1.1: [2] Let G be a matrix Lie group and Let Π_1 be a representation of G acting on a space \mathbb{U} and let Π_2 be a representation of G acting on a space \mathbb{V} . Then the tensor product of Π_1 and Π_2 is a representation $\Pi_1 \otimes \Pi_2$ of G acting on $\mathbb{U} \otimes \mathbb{V}$ defined by: $\Pi_1 \otimes \Pi_2(A) = \Pi_1(A) \otimes \Pi_2(A)$, for all $A \in G$.

MAIN THEOREM

Theorem 1.2: Let G be a matrix Lie group and for each $i \in [1, \dots, n]$, V_i are complex vector spaces over a field F , Π_i are finite dimensional representations of G on V_i then the tensor product representation $\otimes_{i=1}^n \Pi_i: G \rightarrow GL(\otimes_{i=1}^n V_i)$ is completely determine by generators of G and basis of V_i .

Proof: Let s_1, s_2, \dots, s_r be generators of G and $\{V_{1j}\}_{j=1}^{t_1}, \dots, \{V_{nj}\}_{j=1}^{t_n}$ be a basis of V_i where $\dim(V_i) = t_i, i \in [1, \dots, n]$.

Suppose $A \in G$ then $A = s_1^{n_1} * \dots * s_r^{n_r}$ for some $n_1, \dots, n_r \in \mathbb{Z}$.

$$\Pi_i(A) = \Pi_i(s_1^{n_1} * \dots * s_r^{n_r}).$$

Corresponding Author: Saad Owaid*

Department of Mathematics, College of Science, University of Al-Mustansiriyah. Baghdad- Iraq.

If $X \in \otimes_{i=1}^n V_i$, X can be written as ;

$$X = \sum_{j=1}^{t_1} C_{1j} V_{1j} \otimes \dots \otimes \sum_{j=1}^{t_n} C_{nj} V_{nj} \quad (C_{ij} \in F, 1 \leq i \leq n, 1 \leq j \leq \max(t_i)).$$

$$\otimes_{i=1}^n \Pi_{i(A)}(X) = \otimes_{i=1}^n \Pi_{i_1^{n_1} * \dots * s_r^{n_r}}(X) = \otimes_{i=1}^n \Pi_{i_1^{n_1} * \dots * s_r^{n_r}} \left(\sum_{j=1}^{t_1} C_{1j} V_{1j} \otimes \dots \otimes \sum_{j=1}^{t_n} C_{nj} V_{nj} \right)$$

By definition 1.1 above we have:

$$\begin{aligned} &= \Pi_{1s_1^{n_1} * \dots * s_r^{n_r}} \left(\sum_{j=1}^{t_1} C_{1j} V_{1j} \right) \otimes \dots \otimes \Pi_{ns_1^{n_1} * \dots * s_r^{n_r}} \left(\sum_{j=1}^{t_n} C_{nj} V_{nj} \right) \\ &= \left(\sum_{j=1}^{t_1} C_{1j} \Pi_{1s_1^{n_1} * \dots * s_r^{n_r}}(V_{1j}) \right) \otimes \dots \otimes \left(\sum_{j=1}^{t_n} C_{nj} \Pi_{ns_1^{n_1} * \dots * s_r^{n_r}}(V_{nj}) \right) \\ &= \left[C_{11} \Pi_{1s_1^{n_1} * \dots * s_r^{n_r}}(V_{1j}) + \dots + C_{nt_1} \Pi_{1s_1^{n_1} * \dots * s_r^{n_r}}(V_{1t_1}) \right] \otimes \dots \otimes \left[C_{n1} \Pi_{ns_1^{n_1} * \dots * s_r^{n_r}}(V_{n1}) + \dots + C_{nt_n} \Pi_{ns_1^{n_1} * \dots * s_r^{n_r}}(V_{nt_n}) \right]. \\ &= \left[C_{11} (\Pi_{1s_1^{n_1}}(V_{1j}) * \dots * \Pi_{1s_r^{n_r}}(V_{1j})) + \dots + C_{nt_1} (\Pi_{1s_1^{n_1}}(V_{1t_1}) * \dots * \Pi_{1s_r^{n_r}}(V_{1t_1})) \right] \otimes \dots \otimes \left[C_{n1} (\Pi_{ns_1^{n_1}}(V_{n1}) * \dots * \Pi_{ns_r^{n_r}}(V_{n1})) + \dots + C_{nt_n} (\Pi_{ns_1^{n_1}}(V_{nt_n}) * \dots * \Pi_{ns_r^{n_r}}(V_{nt_n})) \right]. \end{aligned}$$

We knew that the set of matrices F_i, H_i and $X_i (1 \leq i \leq 3)$ " listed below", are generators of matrix Lie group SU(2) and basis for the matrix lie algebras **su(2)** and **sl(2)** respectively. In [6] we have computed the adjoint representations resulting from the conjugation action of this group on those algebras where: $Ad_1: SU(2) \rightarrow GL(\mathbf{su}(2)), Ad_2: SU(2) \rightarrow GL(\mathbf{sl}(2))$

$$\begin{aligned} F_1 &= \begin{pmatrix} 0 & 1/2 \\ 1/2 & 0 \end{pmatrix}, F_2 = \begin{pmatrix} 0 & -i/2 \\ i/2 & 0 \end{pmatrix}, F_3 = \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix} \\ H_1 &= \begin{pmatrix} i/2 & 0 \\ 0 & -i/2 \end{pmatrix}, H_2 = \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix}, H_3 = \begin{pmatrix} 0 & i/2 \\ i/2 & 0 \end{pmatrix} \text{ and} \\ X_1 &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, X_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, X_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \end{aligned}$$

Corollary 1.3: $Ad_1 \otimes Ad_2$ can be completely determined by generators of SU(2) and basis of **su(2)** and **sl(2)**.

According to definition 1.1 and corollary 1.3 we have:

Tensor representation $Ad_1 \otimes Ad_2$

The tensor product of the representations Ad_1 and Ad_2 , with the rule

$\Pi_1 \otimes \Pi_2(A, B) = \Pi_1(A) \otimes \Pi_2(B)$, for all $A \in SU(2)$, is given by formula;

$$Ad_1 \otimes dA_2(F_i) = Ad_1(F_i) \otimes dA_2(F_i), \quad 1 \leq i \leq 3.$$

i- $Ad_1 \otimes dA_2(F_1) = Ad_1(F_1) \otimes dA_2(F_1)$

- 1- $Ad_{1F_1}(H_1) \otimes dA_{2F_1}(X_1) = \frac{-1}{4} H_1 \otimes \frac{-1}{4} X_1.$
- 2- $Ad_{1F_1}(H_1) \otimes dA_{2F_1}(X_2) = \frac{-1}{4} H_1 \otimes \frac{1}{4} X_3.$
- 3- $3-Ad_{1F_1}(H_1) \otimes dA_{2F_1}(X_3) = \frac{-1}{4} H_1 \otimes \frac{1}{4} X_2.$
- 4- $Ad_{1F_1}(H_2) \otimes dA_{2F_1}(X_1) = \frac{-1}{4} H_2 \otimes \frac{1}{4} X_1.$
- 5- $Ad_{1F_1}(H_2) \otimes dA_{2F_1}(X_2) = \frac{-1}{4} H_2 \otimes \frac{1}{4} X_3.$
- 6- $Ad_{1F_1}(H_2) \otimes dA_{2F_1}(X_3) = \frac{-1}{4} H_2 \otimes \frac{1}{4} X_2.$
- 7- $Ad_{1F_1}(H_3) \otimes dA_{2F_1}(X_1) = \frac{1}{4} H_3 \otimes \frac{-1}{4} X_1.$
- 8- $Ad_{1F_1}(H_3) \otimes dA_{2F_1}(X_2) = \frac{1}{4} H_3 \otimes \frac{1}{4} X_3.$
- 9- $Ad_{1F_1}(H_3) \otimes dA_{2F_1}(X_3) = \frac{1}{4} H_3 \otimes \frac{1}{4} X_2.$

ii- $Ad_1 \otimes dA_2(F_2) = Ad_1(F_2) \otimes dA_2(F_2)$

- 1- $Ad_{1F_2}(H_1) \otimes dA_{2F_2}(X_1) = \frac{-1}{4} H_1 \otimes \frac{-1}{4} X_1.$
- 2- $Ad_{1F_2}(H_1) \otimes dA_{2F_2}(X_2) = \frac{-1}{4} H_1 \otimes \frac{-1}{4} X_3.$
- 3- $3-Ad_{1F_2}(H_1) \otimes dA_{2F_2}(X_3) = \frac{-1}{4} H_1 \otimes \frac{1}{4} X_2.$
- 4- $Ad_{1F_2}(H_2) \otimes dA_{2F_2}(X_1) = \frac{1}{4} H_2 \otimes \frac{-1}{4} X_1.$
- 5- $Ad_{1F_2}(H_2) \otimes dA_{2F_2}(X_2) = \frac{1}{4} H_2 \otimes \frac{-1}{4} X_3.$

- 6- $Ad_{1F_2}(H_2) \otimes dA_{2F_2}(X_3) = \frac{1}{4}H_2 \otimes \frac{1}{4}X_3.$
- 7- $Ad_{1F_2}(H_3) \otimes dA_{2F_2}(X_1) = \frac{-1}{4}H_3 \otimes \frac{-1}{4}X_1.$
- 8- $Ad_{1F_2}(H_3) \otimes dA_{2F_2}(X_2) = \frac{-1}{4}H_3 \otimes \frac{1}{4}X_3.$
- 9- $Ad_{1F_2}(H_3) \otimes dA_{2F_2}(X_3) = \frac{-1}{4}H_3 \otimes \frac{1}{4}X_3.$

iii-Ad₁ ⊗ dA₂(F₃) = Ad₁(F₃) ⊗ dA₂(F₃)

- 1- $Ad_{1F_3}(H_1) \otimes dA_{2F_3}(X_1) = \frac{1}{4}H_1 \otimes \frac{1}{4}X_1.$
- 2- $Ad_{1F_3}(H_1) \otimes dA_{2F_3}(X_2) = \frac{1}{4}H_1 \otimes \frac{1}{4}X_2.$
- 3- $3-Ad_{1F_3}(H_1) \otimes dA_{2F_3}(X_3) = \frac{1}{4}H_1 \otimes \frac{1}{4}X_3.$
- 4- $Ad_{1F_3}(H_2) \otimes dA_{2F_3}(X_1) = \frac{-1}{4}H_2 \otimes \frac{1}{4}X_1.$
- 5- $Ad_{1F_3}(H_2) \otimes dA_{2F_3}(X_2) = \frac{-1}{4}H_2 \otimes \frac{1}{4}X_2.$
- 6- $Ad_{1F_3}(H_2) \otimes dA_{2F_3}(X_3) = \frac{-1}{4}H_2 \otimes \frac{1}{4}X_3.$
- 7- $Ad_{1F_3}(H_3) \otimes dA_{2F_3}(X_1) = \frac{-1}{4}H_3 \otimes \frac{1}{4}X_1.$
- 8- $Ad_{1F_3}(H_3) \otimes dA_{2F_3}(X_2) = \frac{-1}{4}H_3 \otimes \frac{1}{4}X_2.$
- 9- $Ad_{1F_3}(H_3) \otimes dA_{2F_3}(X_3) = \frac{-1}{4}H_3 \otimes \frac{1}{4}X_3.$

We can display the resulting calculations by the following table (1)

Generators Basis of SU(2)			
Basis Of su(2) ⊗ sl(2)	F ₁	F ₂	F ₃
(H ₁ , X ₁)	$\frac{-1}{4}H_1 \otimes \frac{-1}{4}X_1$	$\frac{-1}{4}H_1 \otimes \frac{-1}{4}X_1$	$\frac{1}{4}H_1 \otimes \frac{1}{4}X_1$
(H ₁ , X ₂)	$\frac{-1}{4}H_1 \otimes \frac{1}{4}X_3$	$\frac{-1}{4}H_1 \otimes \frac{-1}{4}X_3$	$\frac{1}{4}H_1 \otimes \frac{1}{4}X_2$
(H ₁ , X ₃)	$\frac{-1}{4}H_1 \otimes \frac{1}{4}X_2$	$\frac{-1}{4}H_1 \otimes \frac{1}{4}X_2$	$\frac{1}{4}H_1 \otimes \frac{1}{4}X_3$
(H ₂ , X ₁)	$\frac{-1}{4}H_2 \otimes \frac{1}{4}X_1$	$\frac{1}{4}H_2 \otimes \frac{-1}{4}X_1$	$\frac{-1}{4}H_2 \otimes \frac{1}{4}X_1$
(H ₂ , X ₂)	$\frac{-1}{4}H_2 \otimes \frac{1}{4}X_3$	$\frac{1}{4}H_2 \otimes \frac{-1}{4}X_3$	$\frac{-1}{4}H_2 \otimes \frac{1}{4}X_2$
(H ₂ , X ₃)	$\frac{-1}{4}H_2 \otimes \frac{1}{4}X_2$	$\frac{1}{4}H_2 \otimes \frac{1}{4}X_3$	$\frac{-1}{4}H_2 \otimes \frac{1}{4}X_3$
(H ₃ , X ₁)	$\frac{1}{4}H_3 \otimes \frac{-1}{4}X_1$	$\frac{-1}{4}H_3 \otimes \frac{-1}{4}X_1$	$\frac{-1}{4}H_3 \otimes \frac{1}{4}X_1$
(H ₃ , X ₂)	$\frac{1}{4}H_3 \otimes \frac{1}{4}X_3$	$\frac{-1}{4}H_3 \otimes \frac{1}{4}X_3$	$\frac{-1}{4}H_3 \otimes \frac{1}{4}X_2$
(H ₃ , X ₃)	$\frac{1}{4}H_3 \otimes \frac{1}{4}X_2$	$\frac{-1}{4}H_3 \otimes \frac{1}{4}X_3$	$\frac{-1}{4}H_3 \otimes \frac{1}{4}X_3$

Table-1: (Ad₁ ⊗ Ad₂)

2. DUAL REPRESENTATIONS

Definition 2.1: [2] Suppose G is a Lie group and Π is representation of G acting on a finite dimensional vector space V. Then the dual representation Π[^] to Π is the representation of G acting on V[^] given by Π[^](A) = [Π(A⁻¹)]^t, ∀A ∈ G. The dual representation is also called contragredient representation.

Remark 2.2: We can extend our result of theorem 1.2 above to include dual representations which proved in similar procedure, and have the following result:

Proposition 2.2: Let G be a matrix Lie group, V complex vector space over a field F, Π:G → GL(V) be a representation of G on V, then the dual representation Π[^] can be completely determined by generators of G and basis of V.

In particular, proposition 2.2 applies to the dual representations Ad_1^\wedge and Ad_2^\wedge which we compute separately as follows:

Dual representation Ad_1^\wedge

Combining definition 2.1 and proposition 2.2 we have:

1- $Ad_1^\wedge(F_1) = [Ad_1(F_1)^{-1}]^{tr} = [Ad_1(F_1)^*]^{tr} =$
 i- $[Ad_{1F_1^*}(H_1)]^{tr} = [F_1^*H_1(F_1^*)]^{tr} = [F_1^*H_1F_1]^{tr} = \frac{-1}{4}H_1.$
 ii- $[Ad_{1F_1^*}(H_2)]^{tr} = [F_1^*H_2(F_1^*)]^{tr} = [F_1^*H_2F_1]^{tr} = \frac{1}{4}H_2.$
 iii- $[Ad_{1F_1^*}(H_3)]^{tr} = [F_1^*H_3(F_1^*)]^{tr} = [F_1^*H_3F_1]^{tr} = \frac{1}{4}H_3.$

2- $Ad_1^\wedge(F_2) = [Ad_1(F_2)^{-1}]^{tr} = [Ad_1(F_2)^*]^{tr} =$
 i- $[Ad_{1F_2^*}(H_1)]^{tr} = [F_2^*H_1(F_2^*)]^{tr} = [F_2^*H_1F_2]^{tr} = \frac{-1}{4}H_1.$
 ii- $[Ad_{1F_2^*}(H_2)]^{tr} = [F_2^*H_2(F_2^*)]^{tr} = [F_2^*H_2F_2]^{tr} = \frac{-1}{4}H_2.$
 iii- $[Ad_{1F_2^*}(H_3)]^{tr} = [F_2^*H_3(F_2^*)]^{tr} = [F_2^*H_3F_2]^{tr} = \frac{-1}{4}H_3.$

3- $Ad_1^\wedge(F_3) = [Ad_1(F_3)^{-1}]^{tr} = [Ad_1(F_3)^*]^{tr} =$
 i- $[Ad_{1F_3^*}(H_1)]^{tr} = [F_3^*H_1(F_3^*)]^{tr} = [F_3^*H_1F_3]^{tr} = \frac{1}{4}H_1.$
 ii- $[Ad_{1F_3^*}(H_2)]^{tr} = [F_3^*H_2(F_3^*)]^{tr} = [F_3^*H_2F_3]^{tr} = \frac{1}{4}H_2.$
 iii- $[Ad_{1F_3^*}(H_3)]^{tr} = [F_3^*H_3(F_3^*)]^{tr} = [F_3^*H_3F_3]^{tr} = \frac{-1}{4}H_3.$

We can display the resulting calculations as table 2 below.

Basis of $su(2)$ enerators Basis of $SU(2)$	H_1	H_2	H_3
F_1	$-\frac{1}{4}H_1$	$\frac{1}{4}H_2$	$\frac{1}{4}H_3$
F_2	$-\frac{1}{4}H_1$	$-\frac{1}{4}H_2$	$-\frac{1}{4}H_3$
F_3	$\frac{1}{4}H_1$	$\frac{1}{4}H_2$	$-\frac{1}{4}H_3$

Table-2: The dual representation Ad_1^\wedge

Dual representation Ad_2^\wedge

Using the same manner in the case of Ad_1^\wedge above we have:

1- $Ad_2^\wedge(F_1) = [Ad_2(F_1)^{-1}]^{tr} = [Ad_2(F_1)^*]^{tr} =$
 i- $[Ad_{2F_1^*}(X_1)]^{tr} = [F_1^*X_1(F_1^*)]^{tr} = [F_1^*X_1F_1]^{tr} = \frac{-1}{4}X_1.$
 ii- $[Ad_{2F_1^*}(X_2)]^{tr} = [F_1^*X_2(F_1^*)]^{tr} = [F_1^*X_2F_1]^{tr} = \frac{1}{4}X_2.$
 iii- $[Ad_{2F_1^*}(X_3)]^{tr} = [F_1^*X_3(F_1^*)]^{tr} = [F_1^*X_3F_1]^{tr} = \frac{1}{4}X_3.$

2- $Ad_2^\wedge(F_2) = [Ad_2(F_2)^{-1}]^{tr} = [Ad_2(F_2)^*]^{tr} =$
 i- $[Ad_{2F_2^*}(X_1)]^{tr} = [F_2^*X_1(F_2^*)]^{tr} = [F_2^*X_1F_2]^{tr} = \frac{-1}{4}X_1.$
 ii- $[Ad_{2F_2^*}(X_2)]^{tr} = [F_2^*X_2(F_2^*)]^{tr} = [F_2^*X_2F_2]^{tr} = \frac{-1}{4}X_2.$
 iii- $[Ad_{2F_2^*}(X_3)]^{tr} = [F_2^*X_3(F_2^*)]^{tr} = [F_2^*X_3F_2]^{tr} = \frac{1}{4}X_2.$

3- $Ad_2^\wedge(F_3) = [Ad_2(F_3)^{-1}]^{tr} = [Ad_2(F_3)^*]^{tr} =$
 i- $[Ad_{2F_3^*}(X_1)]^{tr} = [F_3^*X_1(F_3^*)]^{tr} = [F_3^*X_1F_3]^{tr} = \frac{1}{4}X_1.$
 ii- $[Ad_{2F_3^*}(X_2)]^{tr} = [F_3^*X_2(F_3^*)]^{tr} = [F_3^*X_2F_3]^{tr} = \frac{1}{4}X_3.$
 iii- $[Ad_{2F_3^*}(X_3)]^{tr} = [F_3^*X_3(F_3^*)]^{tr} = [F_3^*X_3F_3]^{tr} = \frac{1}{4}X_2.$

We can display the resulting calculations as in table 3 below.

Basis of $\mathfrak{sl}(2)$ Generators Basis of SU(2)	X_1	X_2	X_3
F_1	$-\frac{1}{4}X_1$	$\frac{1}{4}X_2$	$\frac{1}{4}X_3$
F_2	$-\frac{1}{4}X_1$	$-\frac{1}{4}X_2$	$\frac{1}{4}X_2$
F_3	$\frac{1}{4}X_1$	$\frac{1}{4}X_3$	$\frac{1}{4}X_2$

Table-3: The dual representation Ad_2^\wedge

REFERENCES

1. Fulton, W., and Harris, J., Representation Theory, A first course , Graduate Texts in Mathematics, Springer-Verlag, New York, INC, 1991.
2. Hall, B. C., "Lie Groups, Lie Algebras and Representations, An Elementary Introduction", Springer, USA, May, 2004.
3. HelmerAslaksen, "Determining summands intensor products of Lie algebrarepresentations", Journal of Pure and Applied Algebra 93 (1994) 135-146.
4. Hall, B. C., "Lie Groups, Lie Algebras and Representations, An Elementary Introduction", Springer, USA, May, 2004.
5. Mahmoud A. A. Sbaih, Moeen KH. Srour, M. S. Hamada and H. M. Fayad, "Lie Algebra and Representation of SU (4)", *Electronic Journal of Theoretical Physics*10, No. 28 (2013) 9–26.
6. Rossmann, W., "Lie Groups; An Introduction Through Linear Groups", University of Ottawa, August, 24, 2005.
7. Saad Owaid and Zainab Subhi, "Representations of SU(2) by the matrix Lie algebras su(2) and sl(2)", to appear, Al-MustansiriyaJ.Sci. 2016.

Source of support: Nil, Conflict of interest: None Declared

[Copy right © 2016. This is an Open Access article distributed under the terms of the International Journal of Mathematical Archive (IJMA), which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.]